# Table of Contents

**SA-A1: System Modeling I**

- Robust Dynamic Operating Model for Supply Chain with Uncertain Product Demands and Raw Material Supplies  
  Jiawang Xu, Xiaoyuan Huang  
  Page 1
- A Multiphase Car-Following Model of Traffic Flow and Numerical Tests  
  Zhipeng Li, Fuqiang Liu, Yuncai Liu  
  Page 6
- MES Disturbance Information Handling Modeling  
  Shuxia Li, Hongbo Shan  
  Page 11
- New Approach of Building GM(1,1) Background Value and Its Application  
  Junfeng Li, Aiping Yang, Wenzhan Dai  
  Page 16
- Neural Networks Model of Polypropylene Surface Modification by Air Plasma  
  Changquan Wang, Xuewu Wang, Xiangning He  
  Page 20
- Research of Return Supply Chain Supernetwork Model Based on Variational Inequalities  
  Zhiping Wang, Fumei Zhang, Zhongtuo Wang  
  Page 25

**SA-A2: Control Theory**

- Non-fragile Multiple-Model Switching Control for Nonlinear Systems  
  Chengshan Qian, Chengzhong Hu, Changsheng Jiang, Yangqiang Wang  
  Page 31
- Dynamic Matrix Control For Integrating System Based on One Point Prediction  
  Haichuan Lou, Wenzhan Dai  
  Page 36
- Optimal RGC Control with Regional Poles and Control Input Constraints: the Actuator Failure Case  
  Dengfeng Zhang, Hongye Su, Shuwen Pan, Zhiquan Wang  
  Page 40
- Filtering of Non-Uniformly Sampled Multirate Systems  
  Jinhai Wang, Hongxia Jiang, Feng Ding  
  Page 46
- Object Tracking Algorithm Based on Camshift Algorithm Combining with Difference in Frame  
  Hongxia Chu, Shujian Ye, Qingchang Guo, Xia Liu  
  Page 51
- Coordinated Control of Urban Expressway Networks via MPC  
  Xuewen Chen, Dianhai Wang  
  Page 56

**SA-A3: Intelligent Control**

- Double-Fuzzy Kalman Filter Based GPS/IMU/MV Sensor Fusion for Tractor Autonomous Guidance  
  Ying Shen, Zhongxiang Zhu, Enrong Mao  
  Page 61
- An Advanced Fuzzy Immune PID-type Tracking Controller of a Nonholonomic Mobile Robot  
  Lingli Yu, Zixing Cai, Zhongyang Jiang, Qiang Hu  
  Page 66
- Formal Programming for the Shortest Path and Its Critical Edge Problems  
  Yujun Zheng, Jinyun Xue, Haihe Shi  
  Page 72
- Theoretical Analysis and Simulation of a Novel Method on Insulation On-line Monitoring of Cross-linked XLPE Electrical Cable at 220kV  
  Zhongjie Liu, Genzhi Guan, Chunlei Shi  
  Page 77
- Development of a Novel Black Box for Tower Crane Based on an ARM-based Embedded System  
  Ming Wang, Guiping Zhang, Qiao Yan, Bin Shen, Liyan Yuan, Liang Liu  
  Page 82
- A New Strategy of Active Fault-tolerant Control for Suspension System of Maglev Train  
  Zhiqiang Long, Xue Song, Zhizhou Zhang, Yunde Xie  
  Page 88
SA-A4: System Optimization I

Combining ICA with SVR for Prediction of Finance Time Series
Jianxin Wu, Jiaolong Wei

Rough Set Based Unstructured Road Detection through Feature Learning
Qingqi Gao, Qijun Luo, Moli Sun

Design and Preparation of Carbon Template with Tailored Porous System
Zhizhong Cui, Dichen Li, Yiping Tang, Jishun Li

Research on Supply Chain Optimization Based on Generic Bills of Materials(GBOM) of Product Family
Zhihong Wang, Xinjian Gu, Guoning Qi

New Multi-objective Genetic Algorithm for Nonlinear Constrained Optimization Problems
Chunan Liu

The Optimization Study on Passenger Organization at Large-scale Passenger Station during Rush Hours Based on Multi-Agent and Cellular Automata
Wei Wang, Xuejun Feng, Yong Wang

SA-A5: Control Application I

Nonlinear Backstepping Design of Ship Steering Controller: Using Unscented Kalman Filter to Estimate the Uncertain Parameters
Yan Peng, Jianda Han, Zhenwei Wu

Scheduling Unrelated Parallel Machine to Minimize Total Weighted Tardiness Using Ant Colony Optimization
Hong Zhou, Zhengdao Li, Xuejing Wu

Application of Wavelet Multi-resolution Analysis to Harmonics Detection Based on MATLAB in Power System
Bingyi Zhang, Haiyan Chen, Ruiguo Chen, Guihong Feng, Haining Zhang

Development of Multifunctional Controller Based on PROFIBUS-DP
Yanjun Fang, Jingyu Liu, Bo Xi

The Design of Guaranteed-Cost Tracking Controller For 3 DOF Helicopter
Tao Shen, Peiran Li, Qingjin Meng, Fengjun Zhang, Xingong Cheng

Model-Based Development Architecture for Embedded CNC System
Zhaogang Shu, Di Li, Feng Ye, Suhua Xiao

SA-A6: Transportation Systems

Measures and Suggestions on Carrying out Automobile Ferrying of Joint land-and-sea Transportation between South Korea and Shandong Province
Yongjie Zhang, Qin Sun

Optimization of Distribution Network with the Constraint of Distribution Radius
Songyan Chen, Jianling Chen, Ding Yao

Routing Problem for Hybrid Hub-and-spoke Transportation Network: a Case Study of a LTL Carrier
Jian Zhang, Yachua Wu, Pei Liu

The Study of Optimized Models and Algorithms of Dynamic Fleet Scheduling Problem
Yaohua Wu, Wumei Zhang, Li Liao

Order Forecast of Cigarette Distribution Center
Yaohua Wu, Zuoqin Song

Study of Business Rules Mining Modeling and Application
Minai He, Na Xu, Peng Liu
SA-A7: Logistics Equipment I

Bio-inspired Robotic Handling of Heterogeneous Logistics Goods
Jose De Gea Fernandez, Jan Christian Albiez, Frank Kirchner

Trust and Knowledge Transfer Between Business Partners: the Mediating Effects of Three Factors
Changli Feng, Tong Zhang

Application of Maximum Principle with Final State Constraints in Gliding Control for Guided Bombs
Lina Geng, Zhiqiang Zheng

Distributed Communication Gateway for Vehicle Distribution System with New Structure
Xiaoqian Hu, Jianping Xing, Weiye Lee, Congfu Bi, Jun Zhang

The Process Modeling and Integration for JIT Automotive Supply Logistics Based on IDEF9000
Huishu Piao, Jie Huang, Chong Wang

Design of Software Based on Middleware for a Lorry Maintenance Line Using Heterogeneous Robots
Pengyu Zhou, Hongjun Song, Yibin Li, Hairong Xiao

SA-A8: Sensors and Data Fusion

Nonlinear Feature Fusion Based on Kernel Fisher Discriminant Analysis for Machine Condition Monitoring
Feng Wang, Xining Zhang, Binggang Cao

Analyzing Human Movements from Silhouettes via Fourier Descriptor
Zhigang Liu, Chunhui Zhao, Quan Pan, Yan Wang, Yongmei Cheng

The Coordinate Acquisition of the Sine Welding Seam based on Zernike Moments Edge Detection
Shiying Gao, Mingyang Zhao, Lei Zhang, Lizhu Wang, Yuanjuan Zou

Realization of Real-time Edge Detection of Weld Pool for YAG Laser Welding in TWB
Lei Zhang, Mingyang Zhao, Lihua Zhao

A Novel Algorithm for Character Segmentation of Degraded License Plate Based on Prior Knowledge
Xiaodan Jia, Xinnian Wang, Wenju Li, Haijiao Wang

Edge Detection Based on Adaptive Structure Element Morphology
Zhe Lv, Fuji Wang, Yuqing Chang, Yang Liu

SA-A9: Robotics I

A Multi-sensory End-effector for Spherical Fruit Harvesting Robot
Jizhan Liu, Pingping Li, Zhiguo Li

Q-learning Based on Neural Network in Learning Action Selection of Mobile Robot
Junfei Qiao, Zhanjun Hou, Xiaogang Ruan

Single Machine Scheduling with Earliness-Tardiness and Completion Time Penalties
Yufang Zhao

Research on Synchronous Control System of Micro Soccer Robot
Zhiyong Tang, Zhongcai Pei, Zhaoqin Peng, Zhanlin Wang

Self-localization of Mobile Robot Based on Binocular Camera and Unscented Kalman Filter
Bao Wei, Changwei Zhang, Benxian Xiao, Rongbao Chen

Study of the New Method for Improving Artificial Potential Field in Mobile Robot Obstacle Avoidance
Enxlu Shi, Tao Cai, Changlin He, Junjie Guo

SA-A10: Automatic Control I

Researches of a Controller for Reducing Load of Driving-chain in Wind Turbine based on H∞ Control
Ying Deng, Shiming Yu, Xiangming Wang, Lei Sun, Jingjing Liang

xxiv
Synchronous Control of Flying-type Welder
Xinruo Sun, Qian Rong, Yongling Fu, Ning Lu

Fault-tolerant Control for Maglev Suspension System Based on Simultaneous Stabilization
Zhizhou Zhang, Zhiquiang Long, Longhua She, Wensen Chang

Research on Micro-feed System in Ultra-precision Grinder
Ruzhong Yan, Beiichi Li, Jianguo Yang, Dengchao Du

ELECTRE III Based on Ranking Fuzzy Numbers for Deterministic and Fuzzy Maintenance Strategy
Decision Problems
Changyou Li, MinQiang Xu, Song Guo

Adaptive Fuzzy Sliding-mode Control in Variable Speed Adjustable Pitch Wind Turbine
Xingjia Yao, Yingming Liu, Changchun Guo

SA-A11: Modeling and Identification I

Point Constraints for B-spline Surfaces Based on Energy Model and Least Square Method
Weijun Liu, Renbo Xia

Suppliers' Channel Choice and the Equilibrium Industry Structure
Zigang Zhang, Zilin Chen, Xubo Zhang

Foreground Detection Based on Real-time Background Modeling and Robust Subtraction
Shengshu Wang, Gewen Kang, Zhi Zhong, Ming Yang, Pei Chen, Yangsheng Xu

Research on Virtual Logistics Enterprise Alliance System Operation Model based on MAS
Liang Zhang, Lixin Shen, Xinlian Xie, Junyu Weng

Multi-Objective Path Selection Model and Algorithm for Emergency Evacuation
Yuan Yuan, Dingwei Wang

Traffic Object Tracking Based on Increased-step Motion History Image
Fanfeng Meng, Zhengshen Qu, Qiangshuang Zeng, Li Li

SA-P1: System Modeling II

A Novel Model of Competition-decision degree and Its Application in Product-Competition Network
Muran Li, Jianmei Yang

A Method for Inter-organizational Business Process Management
Haiying Che, Marco Mervis, Wolfrried Stucky, Yanbin Ju, Ralf Trunko

Customers Mining of Logistics Industry Based on Neuro-Fuzzy Decision Tree
Hongxia Jin, Xiaoye Niu, Li Zhang, Dongyan Zhang

Readiness and Mission Completion Models of Equipment Combat Unit in the Basic Mission
Chenglong Nie, Liu Zhang, Yongli Yu, Huijuan Feng, Shiyong Li

A Robust Model for 3PLS to Design a Remanufacturing Logistics Network under the Uncertain Environment
Yong Zhang, Linjun Xie, Hang Wen, Xiaoyan Cui

Study on Modeling of Unified Power Flow Controller
Wenjin Dai, Zhihong Liu

SA-P2: System Analysis I

An Augmented Optimal Filter for Multi-Channel Stochastic Singular Systems with Multiplicative Noise
Dongsheng Chu, Shouwan Gao, Lina Guo

Decentralized Robust Controller Synthesis for Large Scale System with Uncertainties
Wenqiang Wang, Jianhong Wu

Hybrid Control Strategy for Attitude Stabilization of an Underactuated Spacecraft with Two Moving Mass
Jiang Yu, Fenghua He, Yao Yu
Robust $H_\infty$ Control of Uncertain Sampled-data Systems with Poles Constraint Based on State Observer
Junfeng Wu, Lizhi Dong, Mingbo Jing

Multi-Innovation Gradient Parameter Estimation Based Adaptive Control for Discrete-Time Systems
Jiabo Zhang, Feng Ding, Yang Shi

On $H$-infinity Model Reduction of Continuous Time-delay Switched Systems
Ligang Wu, Weixing Zheng

SA-P3: Evaluation and Optimization I

An Optimal Initialization Technique for Improving the Segmentation Performance of Chan-Vese Model
Renbo Xia, Weijun Liu, Jibin Zhao, Lun Li

A New Trust and Reputation Model for Partner Selection in Virtual Enterprise Based on ASP Platform
Culyu Fu, Aliping Li, Liyun Xu

Viedo-based Measure of Traffic Volume Parameter
Zhenxing He, Zhong Qin, Huiling Wen

K-mean and Double Cross-Validation Algorithm for LS-SVM in Sasang Typology Classification
Qian Zhang, Kijung Lee, TaegKeun Whangbo

Improved Object Tracking with Particle Filter and Mean Shift
KeJia Bai, Weiming Liu

Particle Filter Based Visual Tracking Using New Observation Model
Junyi Zuo, Chunhui Zhao, Yongmei Cheng, Hongcai Zhang

SA-P4: System Optimization II

Implementation of a Quick Fractal Image Compression Algorithm and Its Application in Digital Certificate Solution Scheme
Xiaodong Liu, Yuegong Zhang, Daxing Li

A Multi-Ant Colony System for Vehicle Routing Problem with Time-Dependent Travel Times
Baowen Chen, Shenmin Song, Xinglin Chen

Efficient DNA Algorithms for Chromatic Number of Graph Problems
Xikui Liu, Yan Li

Robust Optimization and Simulation of Production/Inventory System with Stochastic Demand
Ping Zhang, Zude Zhou, Youping Chen, Longyu Ni

Image Segmentation Based on Ant Colony Optimization and K-Means Clustering
Bo Zhao

Chaos Particle Swarm Optimization for Resource Allocation Problem
Su Wang, Bo Meng

SA-P5: Control Application II

Study on Message Zero-Copy Communication and Protocol among Multi-DSPs
Baoshan Ge, Bo Li, Wensheng Zhang, Yang Zhang

An Acoustic Echo Cancellation Technique Based on Kurtosis Subgradient Projection Algorithm
Jie Qiao, Li Zhao, Cairong Zou

A Novel Design of Distributed Servo System Based on Rearranging Functions between Host Controller and Servo Driver
Daguang Shi, Baoren Wang, Hongen Wu

Application of Double Model Control Scheme based on RBF Inverse Identification in Electrode System of Electrical Arc Furnace
Shaode Zhang, Xiao Zheng
Research on Applications of a new-type fuzzy-neural Network Controller
Xucheng Dong, Qiang Xu, Xiaoxiao Zhao

Medical Video Stream Transmission in Telemedicine
Fan Zhang, Bo Li

SA-P6: Intelligent Transportation System I

Determination of Capacity at Two-Way Stop-Controlled Urban Intersections
Haiyuan Li, Wei Deng

On-ramp Metering on Beijing Urban Expressway
Xuewen Chen, Dianhai Wang, Sheng Jin

A Hybrid Prediction for Non-Gaussian Self-Similar Traffic
Yong Wen, Guangyi Zhu, Changsheng Xie

The Optimization Design of Urban Traffic Signal Control Based on Three Swarms Cooperative-particle Swarm Optimization
Yongsheng Qian, Chunlei Wang, Hailong Wang, Zhetang Wang

Research and Realization of the Optimal Path Algorithm with Complex Traffic Regulations in GIS
Qianyu Wang, Linhui Xu, Jiandong Qiu

Application of Multi-agent Technology in Decision-making System for Vessel Automatic Anti-collision
Shenhua Yang, Chaojian Shi, Yuhong Liu, Qinyou Hu

SA-P7: Logistics Equipment II

Formal Specification for Secure Electronic Data Interchange System in Maude
Junfeng Wu, Huailkou Miao

Experiment Study of Multi-Step Predictive Control in AGV Path Tracking
Enxiu Shi, Junjie Guo, Changlin He, Tao Cai

Selection of AS/RS Scheduling Rules Based on Genetic Algorithm
Wen Wang, Weiping Fu, Mingyun Ma, Dexin Li, Shiqlang Yang

Design and Control Technique Research of Exoskeleton Suit
Lihua Gui, Zhiyong Yang, Xiuxia Yang, Wenjin Gu, Yuanshan Zhang

Public Data Service System Based on Lighting Networks
Chengyu Jiang, Yuxian Gai, Jing Guo, Bo Wang, Qiankun Yang

Research on Goods Locations Distributing Optimization for Tobacco AS/RS
Changyou Zhao, Yun Yang, Jianfeng Li

SA-P8: Robotic Systems I

Transplantable CANopen Master Based on Non-preemptive Task Scheduler
Wei Song, Shizhen Yan, Zhe Xu, Suiming Fang

Optimal Design of Parallel Robots for the Prescribed Regular Dexterous Workspace
Zhongfei Wang, Shiming Jì, Yuehua Wan, Changlin Ou, Jianhui Sun, Guan Wang

Formation Control and Obstacle Avoidance Algorithm of Multiple Autonomous Underwater Vehicles (AUVs) Based on Potential Function and Behavior Rules
Qiuling Jia, Guangwen Li

A Monocular Visual Servoing System for Mobile Robot
Jie Yang, Mingjun Zhang, Yujia Wang, Yunchao Shang

B-2WMR System Model and Underactuated Property Analysis
Xiaogang Ruan, Jing Chen

Design of a Flexible Manipulator controller Based on Input-output Linearization
Ying Sun, Runzhi Wu, Fangxiao Cheng, Zhenyuan Gao, Lan Yu
SA-P9: Robotics II

A Method On Obstacle Object Recognition For Indoor Mobile Robot Based On Feature-Line Flows
Zhenhua Wei 591

Research on A Novel R-8 Wafer-Handling Robot
Ming Cong, Xu Yu, Baohong Shen, Jing Liu 597

Study on Object Operating System for Service Robot Based on Artificial Marks
Xiaolei Li, Guohui Tian, Hongtao Xue, Fei Lu, Pan Zhang 603

Robot Heterogeneity Analysis Based on Extentics
Wu Hao, Guohui Tian 608

3D Kinematic Simulation for PA10-7C Robot Arm Based on VRML
Weimin Shen, Jason Gu, Yide Ma 614

Feature Fusion Method Based on KCCA for Ear and Profile Face Based Multimodal Recognition
Xiaona Xu, Zhichun Mu 620

SA-P10: Automatic Control II

A New Guidance Law based on Information Fusion and Optimal Control of Structure Stochastic
Jump System
Mars Moon 624

Study on Mixed H\infty/H2 Control for Enhancing the Tracking Performance of EPS
Wanzhong Zhao, Guobiao Shi, Yi Lin 628

Generalization of the Theorems of Alternatives in Semidefinite Programming
Yiping Cheng 634

Vehicle Lateral Stability Control Based on Sliding Mode Control
Shuen Zhao, Yirong Li, Ling Zheng, Shaobo Lu 638

Fuzzy Neural Network PID Control for Electric Power Steering System
Huaiquan Zhang, Min Liu 643

The Application of Generalized Predictive Control in CVT Speed Ratio Control
Jingang Liu, Yunshan Zhou, Naiwei Zou 649

SA-P11: Modeling and Identification II

Modeling and Forecasting Engine Air Induction under Transient Condition Based on Information
Fusion
Yihu Wu, Huanchun Gong, Zhixiang Hou, Yuan Hou 655

Research on the Multi-echelon Inventory Model of Weapon Equipment Repairable Valuable Spare
Parts
Jiangsheng Sun, Yanmei Lv, Sujian Li, Fanggeng Zhao 662

Traffic Flow Predicting of Chaos Time Series Using Support Vector Learning Mechanism for Fuzzy
Rule-based Modeling
Mingbao Pang, Guoguang He 666

A Transit Network Assignment Model Based on Congestion and Preference
Huimin Niu, Zhihong Mao 671

Extension Similar Method of Maintenance Manpower Requirement Forecast for a Mission
Ying Xu, Yongli Yu, Jun Yang 676

Reliability Prediction Model of Aircraft using Self-Organizing Map
Jingjie Chen, Jiusheng Chen, Xiaoyu Zhang 680

SA-E1: System Modeling III

Anti-Dumping Early-Warning Model Based on Rough sets and Neuro-FDT
Jianna Zhao, Xu Zhao 684

xxviii
Resource Modeling of Logistic Grid System Based on XML
Xiuwu Zhao, Fei Tao, Yefa Hu, Zudfe Zhou

Deterministic Deteriorating Product's Production-Inventory Model With Variable Productivity
Rongguo Luo

Business Process Modeling for Multi-enterprise Cooperation
Hongxiu Wang, Gang Wang, Xiaoxian Wen, Guoan Gao

An Optimization Model of Container Marine Transport with COA Approach
Wenyuan Wang, Xiangqun Song, Zijian Guo, Buxin Fu

Econometric Modeling of Second-Hand Tanker Prices
Ming Zhong, Shi Qin

SA-E2: System Analysis II

Decoupled Control of the Active and Reactive Power in Three-phase PWM Converter based on Inverse System Theory
Jiahua Guo, Luhua Zhang, Fujing Deng

Robust Stability Analysis of Time-varying Parameter Polynomial-dependent Linear Systems
Na Li, Keyou Zhao, Mingting Yuan

Parameter-dependent Lyapunov Function Approach to Stability Analysis for Discrete-time LPV Systems
Na Wang, Keyao Zhao

State Observer and Robust Control for Uncertain Systems with Unknown State Delay
Yangqi Cui, Tao Zhang, Jinsong Sun

The Control Systems of Secondary regulation and Theirs Coupling and Decoupling Characteristics Analysis
Xiangdong Kong, Long He, Yingjie Gao, Zhang Qin

Research on the Algorithm of Adaptive Coupling Control and Synchronization for a Kind of Continuous-time Chaos System
Xiuqi Pan, Yongtun Cao, Yong Lu, Yue Zhao, Hong Zhang

SA-E3: Evaluation and Optimization II

Recognizing the Main Steam Temperature System using Genetic Programming with Automatically Defined Functions
Yiheng Jiang, Yan Bai, Yaochun Zhu

A New Continuous Petri Net: Step Continuous Petri Nets
Shouguang Wang

Multi-sensor Optimal Information Fusion Estimation under One-step Random Sensor Delay
Rongli Liu, Jing Hu, Chenglin Wen

A New 3D Evaluation Approach of Practical Airside Capacity at Airports
Chengyuan Zhu, Haifei Zhang

Dynamic Combined Evaluation Method and its Application in Supplier Selection
Xuejun Wang, Jing Hao

Study on Parameter Optimization of Polypropylene Surface Modification in Atmospheric Pressure Dielectric Barrier Discharge
Changquan Wang, Xuexu Wang, Xiangning He

SA-E4: System Optimization III

An Optimization Model for Intra-Bay Relocation of Outbound Container on Container Yards
Yanwei Zhang, Wei Jian Mi, Daofang Chang, Wei Yan, Laide Shi
The Application of Immune Genetic Algorithm in PID Parameter Optimization for Level Control system
Chengwei Tang, Jiandong Lian 782

Bi-ACO: A Tool for Solving Bi-Criteria Optimization
Shidong Wang 787

Image Segmentation with 2-D Maximum Entropy Based on Comprehensive Learning Particle Swarm Optimization
Weihua Liu, Qingmei Sui, Wei Zhang, Nan Lu, Zhengmin Liu 793

A Novel Simplified Foraging Optimization Algorithm for Parameter Identification of Nonlinear System Model
Yanjun Fang, Yijian Liu, Jingyu Liu 798

Stiffness Optimization Design of a Light Space Manipulator
Hongliang Jia, Weimin Zhang, Qiang Huang, Jianxi Li 803

SA-E5: Flow Shop Scheduling
Scheduling Hybrid Flow Shop for Minimizing Total Weighted Completion Time
Cong Gao, Linlin Tang 809

Research on Work Flow Optimization and Visualization System
Weizhuo Lu, Yaowu Wang, Bing Yao 814

Dynamic Constraint Satisfaction Approach to Hybrid Flowshop Rescheduling
Tieke Li, Yongjun Xiao, Hailong Wang 818

A Particle Swarm Optimization Algorithm for Robust Flow-Shop Scheduling with Uncertain Processing Times
Bing Wang, Zhen Yang 824

Rolling Horizon Procedure for the Large-scale Job Shop Scheduling Problem
Bing Wang, Qiaoyun Li 829

An Adaptive Policy of Dynamic Scheduling in Knowledgeable Manufacturing Environment
Hongbing Yang, Hongsen Yan 835

SA-E6: Intelligent Transportation System II
Novel Traffic Control System & Its Coordination Model Based on Large-scale Systems
Yuan Wang, Zhaosheng Yang, Qing Guan 841

Nonlinear Characteristics of Short-term Traffic Flow and Their Influences to Forecasting
Jun Zhang, Jun Liu 847

A Novel Division Based Self-Motion Algorithm for Avoiding Obstacles for Redundant Manipulators
Chengkun Zhang, Hanxu Sun, Qingxuan Jia, Lei Hong 852

Based on the Cusp Catastrophe to Research the Relationship among Traffic Flow Three Parameters
Jian Guo, Xinglin Chen, Hongzhang Jin 858

Research on the Prediction of Urban Passenger Transport based on Support Vector Machine
Wenfeng Zhang, Zhongke Shi, Qin Liu 862

A System Architecture to SOA-Based 4PL Using RDF
Wenlan Tan, Fujun Yang, Ruibin Chen, Xianhua Zhao 866

SA-E7: Logistics Equipment III
Study and Prospect on Integrated Multi-technology in Logistics
Chengxin Yu, Mingwen Chen, Mingqiang Chen, Shiguang Li, Shaolin Li 871

Study of Computer Vision and Robot Control Technology in AS/RS
Chengxin Yu, Li Zhao, Na Xu, Shaolin Li, Yunchang Gao 876
The Research of the Enterprises Logistics Information Platform Framework Based on the E-Commerce
Danyu Zhang, Jian Zhang

Study on the Pallet-bank and its Construction
Shousong Jin, Meixian Jiang, Zhenxiang Yao, Haqing Ge, Dingzhong Feng

Study on the Application of Six Sigma Method in Logistic Corporation
Yuan Zhang, Yan Xu, Zheng Wan

The Study and Design of Communication Service of Vehicle Monitoring System
Danyu Zhang, Hongfeng Gao

SA-E8: Robotic Systems II

Research on Application of Genetic Algorithm for Intelligent Mobile Robot Navigation Based on Dynamic Approach
Shiqiang Yang, Weiping Fu, Dexin Li, Wen Wang

Fault Diagnosis Method for Mobile Robots: Using Multi-CMAC Neural Networks
Yutian Liu, Jingping Jiang

The Design and Simulation of Fuzzy Logic Controller for Parallel Hybrid Electric Vehicles
Qun Zeng, Juhua Huang

Design of the Master-Slave System and Research on Bilateral Servo Control System of Tele-Operated Manipulation Robots
Zhuxin Zhang, Dingxuan Zhao, Tiehua Chen

Motion Control of Mini Underwater Robots Based on Sigmoid Fuzzy Neural Network
Xiao Liang, Bingjie Guo, Lei Wan

Formation Path Tracking Controller of Multiple Robot System By High Order Sliding Mode
Qiuling Jia, Xiaojun Xing, Guangwen Li

SA-E9: Process Automation I

Co-simulation on Automatic Pouring of Truck-mounted Concrete Boom Pump
Shuwen Zhou, Siqi Zhang

Simulation Tool for Factory Numerical Equipment Control System Network Based on EPA protocol
Xiuju Wu, Gangyan Li, Liping Lu

The Controller Tuning and Process Identification for Multivariable System
Yongguo Zhao, Lei Jia

Modeling and Analysis of the Active Vibration Isolation with Giant Magnetostrictive Actuator
Xuhui Zhang, Yongfeng Fu, Yongguang Liu

The Welding Power Supplies Group Control System Based on T-S Model and ANFIS
Zhangfeng Zhao, Jian Feng, Xian Zhang, Yangyu Wang

Stiffness Analysis and Experiment of a Parallel Kinematic Planer
Hongjun Liu, Changlong Ye, Hequan Wang, Yingzhi Wang

SA-E10: Intrumentation Systems I

An Experimental Investigation into the Design of Vehicle Fuzzy Active Suspension
Farong Kou

Automatic Measurement and Control System for Vehicle ECU Based on CAN Bus
Feng Kong, Liyan Zhang, Jie Zeng, Yuhua Zhang

A Novel Non-sinusoidal Compensation of Transformer Based on Core Loss and Magnetic Saturation Model
Aiyuan Wang

Robust $\mu$ Control System for The Optical Ultra Precision Vibration Isolation System
Zhenyu Lu, Rihong Zhu
A Novel Linear Actuator and Its Controlling System
Qingxin Zhang, Fengxiang Wang

Fault Diagnosis of Hydraulic Actuator Based on Least Squares Support Vector Machines
Liangmou Hu, Keqiang Cao, Haojun Xu, Baorui Li

SA-E11: Identification and Simulation I

Parameter Evaluation and Prediction in Information Poor System using Fuzzy-set Theory
Xintao Xia, Long Chen, Yujun Xue

Design and Kinematics Analysis of Oblique Axis Non-spherical 3R Wrist
Zhanzhong Wang, Dawei Zhang, Hongzhi Han

Model Analysis and Computer Simulation Study for Feeders of the High-speed Package Sorter
Xiaoguang Zhou, M. Tsutsuji

Parameter Estimation for Hammerstein Nonlinear Controlled Auto-Regression Models
Wei Fan, Feng Ding, Yang Shi

Simulation and Analysis of Complex Vibration Isolation System
Dezhun Feng, Yuru Wang, Ying Gao

PC Based High Quality and Low Cost Flight Simulator
Lei Zhang, Hongzhou Jiang, Hongren Li

SU-A1: System Modeling IV

The Dynamic Model of Doubly-fed Induction Generator Based on Wind Turbine
Xingjia Yao, Hongxia Su, Zuoxia Xing, Dayong Liu

A Venture Investment Principal-agent Model Base on Game Theory
Xubo Zhang, Zigang Zhang

A Memory Efficient Simplification Algorithm of Polygonal Meshes
Yongsheng Zhao, Lingyun Li, Lihua Song

Vision-based Vehicle Type Classification Using Partial Gabor Filter Bank
Peijin Ji, Lianwen Jin, Xutao Li

A Simulation Study of Logistics Activities in Mixed-model Assembly Lines with Genetic Algorithm
Wenping Liu, Zhaofang Jiang, Guicong Wang, Zhaqian Li

Studies on Hierarchical Modeling of Solar Cells Manufacturing System Based on Simulation
Wenhua Zhu, Sufen Du

SU-A2: Automation I

Research on Adjust Speed Control System of Partial Fan
Shufang Wang, Jianbo Wang, Ruiyang Xin, Feng Chen

The Optimization of PID Controller Parameters Based on Artificial Fish Swarm Algorithm
Yi Luo, Juntao Zhang, Xinlin Li

Study of High Order Differential Feedback Control of DC-link Voltage in Active Power Filter
Wei Xue, Yanjun Xue, Guoyuan Qi, Jianqiang Gao

Overview of Research on Assessment Model of Radiant Threat Rank Based on Dynamic Bayesian Network
Tang Zheng, Xiaoguang Gao, Ying Zhang

Hybrid Diagnosis Method based on Evolutionary Algorithm and Support Vector Machines
Wei Ding, Xunkai Wei, Liming He

Transformer Power Fault Diagnosis System Design Based on the HMM Method
Suxiang Qian, Weidong Jiao, Hongsheng Hu, Gongbiao Yan
SU-A3: Evaluation and Optimization III

Research on the Convergent Performance of the Auxiliary Problem Principle Based Distributed and Parallell Optimization Algorithm
Lixia Cao, Yan Sun, Xingong Cheng, Baoliang Qi

Games Analysis of Prevent Insiders Control Effectively
Zhiyong Gong, Dingan Li, Fan Qi

Analysis on Local Railroad Freight Transportation’s the Unit Root Process of Structural Changes
Hanli Chen, Chaoqun Ma, Tao Qin

A Multi-attribute Decision-making Method with Interval-numbers and its Application
Lin Liu

Research on After-Sale Services Evaluation Based-Analytic Hierarchy Process and Fuzzy Comprehensive Evaluation
Tianbiao Yu, Zixu Liu, Jing Zhou, Jianrong Wang, Wanshan Wang

A Quantitative Approach for Conflict Identification and Its Application in Appraising Strategic Partners
Mingrong Deng, Weixuan Xu

SU-A4: System Optimization IV

The Research and Application of LS_SVM Based on Particle Swarm Optimization
Yongqi Chen, Zhanxin Zhou, Qijun Chen

Chaotic Particle Swarm Optimization Algorithm for Travelling Salesman Problem
Zhenglei Yuan, Liliang Yang, Yaohua Wu, Liao Li, Guoqiang Li

Optimal Sizing of a Series Hybrid Electric Vehicle Using a Hybrid Genetic Algorithm
Xudong Liu, Yanping Wu, Jianmin Duan

Production Planning Decision Based on the Optimized Fuzzy Time-series Clustering
Junping Li, Bo Li, Limei Xu, Shamin A Shirodkar

Optimizing Gate Assignment at Airport Based on Genetic-Tabu Algorithm
Dongxuan Wei, Changyou Liu

The Optimization of DNA Encoding Sequences Based on Improved AFS Algorithms
Guangzhao Cui, Xianghong Cao, Junhe Zhou, Yanfeng Wang

SU-A5: Supply Chain Management I

Consumers Risk Control in a Collaborative Supply Chain
Huimings Zhu

Risk Management of Global Supply Chain
Dan Wang, Zan Yang

Research on Quality Management System for Individualized Customization Based Customer Satisfaction
Xingyu Jiang, Shuang Liang, Wei Ding, Wanshan Wang

The Analysis of Signaling Game in Reverse Supply Chain
Gongjian Kan, Yuyuan Wang

A Hybrid BPSO Algorithm for Lot Sizing and Scheduling Problem of Cold Rolling Production
Tieke Li, Cantao Shi

Distributed Cooperative Planning and Scheduling for Disaster Management
Yujun Zheng, Jinquan Wang, Jinyun Xue

SU-A6: Dynamic Scheduling

Dynamic Scheduling of Oil Refinery based on Model-optimization and Process-configuration
Qingqiang Guo, Qiqiang Li, Ran Ding, Jinsong Zhang, Xiuhong Wang
Study on Dynamic Priority Scheduling Based on Fuzzy Logic for Networked Control Systems
Baoren Wang, Daguang Shi, Lei Jia, Jie Wang, Longhai Tan

Optimizing Pricing Functions for Metro in a Competitive Public Transport System
Feifei Qin, Haicheng Jia

A Path Planning Algorithm Based on Dynamic Networks and Restricted Searching Area
Mengyin Fu, Bin Xue

The Research of Dynamic Path Planning for Centralized Vehicle Navigation
Hong Wei, Yantao Tian, Yong Xu

User Interface Knowledge Reuse and Multi-device User Interface Development
Shihong Feng, Jiancheng Wun

SU-A7: Logistics Equipment IV

Research of Efficiency Optimization in Tobacco Automated Sorting System
Yigong Zhang, Yaohua Wu

The Optimize Tactic and the Simulation of the Fast sorting system
Bingqing He, Minde Shen, Yingying Wu

The Design of Vehicle Emergent Calling System Based on GPRS
Yuqi Hu, Yang Liu, Huaiquan Zang

The Simulation Research on Stacker Control in Airport Logistics System
Jianjun Meng, Chenghui Yang

Modeling and Simulation of a Multi-Echelon Inventory System for a Manufacture Firm
Meilian Liu, Feng Zhang

Research on a Digital Watermarking Algorithm Suitable to Vector Map
Shujun Deng, Liang Lu, Che Sen, Shujun Deng

SU-A8: Robotic Systems III

The Research on Multi-robot Simultaneous Localization and Mapping Algorithm
Zhenhua Wei

A Trajectory Generator for a Mobile Robot in 3D Pathplanning
Changan Liu, Wengang Chen, Hong Zhou

Distributed Adaptive Sliding Mode Control of Modular and Reconfigurable Robots
Mingchao Zhu, Ying Li, Yuanchun Li

An Efficient Needle Insertion Robotics System for Ultrasound-guided Hepatic Microwave Coagulation Therapy
Jing Xu, Xiangdong Yang, He Ren, Dan Wu, Ken Chen, Ping Liang

Development of a Mobile Platform for Security Robot
Dehuai Zeng, Gang Xu, Jinming Zhong, Li Li

Research on Conflict Issues and Clearing up Techniques in Collaborative Design System
Ruisu Liu, Chunjie Xu, Guolin Duan, Kai Li

SU-A9: Process Automation II

Research and Application of Information System Architecture in Cement Enterprises
Shaojiong Jing, Qingjin Meng, Wenqian Cao, Hongjian Chen

Study of MES for Cement Industry
Xiaohong Wang, Li Sun, Qingjin Meng, Wenqian Cao

An Intelligent Supervisory System for the Thermal Processes during Severe Disturbance
Yun Zhang, Hongbo Liu, Jia Lei

Integral Fuzzy Sliding Mode Control for Variable speed wind power system
Xiyun Yang, Xinran Liu, Qing Wu
Experimental and Technical Study of Fiber Bragg Grating Vibration Detection Based on Linear Tilt Filter Method
Qi Jiang, Qingmei Sui, Jing Wang
Experimental and Technical Study of Fiber Bragg Grating Vibration Detection Based on Matching Demodulation Method
Qi Jiang, Qingmei Sui, Jing Wang

SU-A10: Instrumentation Systems II
Research on a Conceptual 6-DOF Camera Manipulator Mounted on the Space Capsule
Hanxu Sun, Chengkun Zhang, Lei Hong, QingXuan Jia
Based on digital image lane edge detection and tracking under structure environment for autonomous vehicle
Feng You
The Design of a High Cost Performance Piston outside Diameter Auto-measuring and Grouping System
Musheng Yang, Yu Zhang, Jinxing Bai
An Automatic Test Instrument for Dial Gauge Based on Computer Image Process
Musheng Yang, Rong Chen, Yu Zhang
Application of X-ray Computed Tomography to Automatic Wood Testing
Shuxia Han, Lei Yu, Dawei Qi
Experimental study of coupling fiber-optic vibration sensor
Bin Ma, Qingmei Sui, Hongliang Cui, Xiaoyang Huang

SU-A11: Identification and Simulation II
Linear System Identification Employing Independent Component Analysis
Shifeng Ou, Xiaohui Zhao, Ying Gao
Feature Extraction of the Noise in L-PLC
Zhenchao Wang, Huiran Hou, Yu Tao Gan
Simulation and Optimization Research on Good-sized Auto Fittings’ Production-Inventory System
Xuping Wang, Hai Zhao, Hongyan Shang
Simulation Research of Exoskeleton Suit Based on Sensitivity Amplification Control
Zhiyong Yang, Lihua Gui, Wenjin Gu, Xiuxia Yang, Yuanshan Zhang
Simulation of Automatic Addressing Behavior Based on Urban Residential Land
Yuhong Shan, Xin Yan Zhu
Application of the Naive Bayesian Method with User Current Usage and Hierarchy from Website in Chinese Webpage Classification
Jinsong Li, Weimin Xue, Nanping Dong

SU-P1: System Identification I
Research on Chatter Prediction and Monitor Based on DHMM Pattern Recognition Theory
Jing Kang, Changqian Feng, Qiang Shao, Hongying Hu
Short-Term Load Forecasting Model For Power System Based on Complementation of Fuzzy-Rough Set Theory And BP Neural Network
Peng Chen, Qing Zhang
The Data Acquisition and Analysis System of Grating Geophone Based on FPGA
Shuqing Li, Guanya Wang
One Method of Bearing Outside-Diameter Detection Based on Hough Transform
Fei Zhong, Na Dai, Tao He, Qinghua Wu
Revenue-sharing Contracts in Assembly Systems with Fuzzy Demand
Junyan Wang, Wansheng Tang, Ruiqing Zhao
SU-P2: Automation II

Development of an FPGA-Based Servo Controller for PMSM Drives
Yan Li, Shengxian Zhuang, Luan Zhang

On the Design Approach of Robust Sliding mode Observers by Using Linear Matrix Inequalities
Zhongyu Shen, Jin Zhao, Xingsheng Gu

Research on Cooperative Control Methods of Saturation Attack
Jinhua Wu, Peibei Ma, Jun Ji

Current State and Prospect of Micro-Machining
Xiaoxia Li, Jiuhong Wang, Wen Li

Comparative Analysis of Variable Ordering Heuristics for Job-Shop Constraint Satisfaction Problem
Jing Yin, Tieke Li

Periodic Orbit Analysis of Switched Linear Systems
Jingya Su, Xinhua Wang, Kaiyuan Cai

SU-P3: Evaluation and Optimization IV

Optimal Design of Online Auctions
Shengli Chen, Huiqiu Wu, Yunfeng Luo

Research on Multi-Objective optimal tuning of Auto-Disturbance-Rejection-controller
Dehui Sun, Yuntao Shi, Zhijun Li, Jiuru Zuo, Dongjie Gao

Supply Chain Risk Evaluation Based on Fuzzy Multi-Criteria Lattice-Order Decision-Making
Wen Lei, Zhaocai Xi

An Application of ANP with Benefits, Opportunities, Costs and Risks in Supplier Selection: A Case Study in a Diesel Engine Manufacturing Firm
Xuguang Tan, Ke Ma, Wei Guo, Tian Huang

A fuzzy-ANP approach to cooperation risk evaluation of virtual logistics enterprise
Xiaoyan Cui, Feng Wang, Xuhong Li, Yong Zhang, Shijun Yu

Ground Moving Target Tracking Control System Design for UAV Surveillance
Zhongjian Li, Jiariui Ding

SU-P4: Signal Filtering

Study on Differential Equation and Solution of Throttle Slice Deformation of Shock Absorber
Changcheng Zhou, Baojiang Kang, Wei Xu

Optimal Design for Passive Power Filters in Hybrid Power Filter Based on Particle Swarm Optimization
Lina Huang, Na He, Dianguo Xu

Robust H-infinity Filtering on Uncertain Systems
Ping Sun, Chunyu Liu

The State Estimation for Electric Stability Program Using Kalman Filtering
Yuxian Gai, Qingti Guo, Huaying Liu

Robust Least Square Method and its Application to Parameter Estimation
Mei Zhang, Chenghui Zhang, Huanshui Zhang, Peng Cui, Yanchun Du

Time Series Forecasting Based on Wavelet KPCA and Support Vector Machine
Fei Chen, Chongzhao Han

SU-P5: Supply Chain Management II

The Designation of Agriculture Supply Chain Management DSS
Yujuan Sun, Yilei Wang, Tao Li
Optimal Order Policies in a Custom-made Product Supply Chain with Substitution and Market Signal
Yan Wang, Chengxiu Gao, Suzhen Li

Decisions of Inventory and Pricing on Products with Substitution
Jing Zhao, Jie Wei, Yancong Zhou, Cansheng Wei

Study on Foundation of Simulation Test Bed for Uncertainty in SCM
Dawei Liu, Yongquan Zhao

Study on Supply Chain Management for Product Family in Mass Customization
Zhihong Wang, Fanghua Ning

An Innovative Mode of Supply Chain Management in Tsinghua University Press
Qiqi Sun, Changxin Xu, Wanzhu Hong, Yan Wang, Xiuying Ni

SU-P6: Distribution Systems
Bridge Monitoring System Based on Distribution Network Sensor
Baoping Chen, Ming Yang, Weiguo Di, Yuebo Wang

Extending Distributed Simulation's Run-Time Infrastructure with Web Services
Zebin Wu, Huizhong Wu, Weiqing Li, Xu Zhang

Fuzzy Programming Model and Algorithm for Optimal Design of Distribution Centers for B2C E-commerce
Zhongzhong Jiang, Dingwei Wang, W.H Ip

The Applied Research Based on Decision Tree of Data Mining In Third-Party Logistics
Qian Wang, Yaohua Wu, Jiwei Xiao, Guangfeng Pan

A Flexible Architecture for Representing Personality in Distributed Systems Development
Xue Xiao, Zhi Sun

A Genetic Algorithm for the Capacitated Arc Routing Problem
Xin Deng, Zhengyu Zhu, Yong Yang, Xiaohua Li, Yunyan Tian, Mengshuang Xia

SU-P7: Pattern Recognition
An Edge-Detection Method for Moving Objects
Jing Zhang, Ying Shan, Maozu Guo

A Contourlet-based Method for Handwritten Signature Verification
Ming Yang, Zhongke Yin, Zhi Zhong, Shengshu Wang, Pei Chen, Yangsheng Xu

Human Cast Shadow Elimination Method Based on Orientation Information Measures
Sheng Bi, Dequn Liang, Xiaoyan Shen, Qiang Wang

Pedestrian Detection using KPCA and FLD Algorithms
Yinghong Liang, Zhiyan Wang, Sen Guo, Xiaowei Xu, Xiaoye Cao

Segmentation of On-line Cursive Handwritten Chinese Word Based on Stroke Speed Feature and Stroke Vector Feature
Rui Guo, Lianwen Jin

Face Feature Extraction Based on Principle Discriminant Information Analysis
Jianqin Yin, Yuelong Li, Jinping Li

SU-P8: Robotic Systems IV
Design of DSP-based Open Control System for Industrial Robot
Bo You, Dongjie Li, Suju Liu

Sergiu-Dan Stan, Vistrian Maties, Radu Balan

Design of Vehicle Control Unit Based on DSP for a Parallel HEV
Weimin Li, Guoqing Xu, Hang Tong, Yangsheng Xu
Simultaneous Localization and Mapping for Autonomous Mobile Robots Using Ultrasonic Range Finder and Monocular Vision
Huiling Liu, Lufang Gao, Yuxian Gai, Sheng Fu

Implementation of Basic Reactions for a Miniature Surveillance Robot
Changhe Zheng, Yuancan Huang, Qiang Huang, Yibo Liu, Liang Wang

Mechanical Design and Dynamic Modeling of a Two-Wheeled Inverted Pendulum Mobile Robot
Jingtian Li, Xueshan Gao, Qiang Huang, Qinjun Du, Xingguang Duan

**SU-P9: Process Automation III**

Design of Intelligent Automatic Leveling Control System Based on Ultrasonic Distance Measuring Technology
Jie Liang, Zhiguang Guan

A Novel Immune Feedback Controller and Its Applications for Main Steam Temperature System
Daogang Peng, Hao Zhang, Ping Yang, Hui Li

FPGA-Based Single-Chip Servo System for Five Axes Actuators
Shuang Wang, Tiecai Li, Zhaoyong Zhou

Application of PCA Method and FCM Clustering to the Fault Diagnosis of Excavator's Hydraulic System
Xiangyu He, Qinghua He

Intelligent Integrated Control Method in Manufacturing Process
Musheg Yang, Yu Zhang

Integrated Computer-aided Control and Optimization of Béchamel Production Processes
Xiaoyan Chen

**SU-P10: Intrumentation Systems III**

Applications of Fiber Optic Bragg Grating Sensing Technology in a Forked Tunnel Model
Tianying Chang, Dongsheng Li, Qingmei Su, Lei Jia, Zhanxiang Wei, Hongliang Cui

Vision-Based Profile Generation Method of TWB for a New Automatic Laser Welding Line
Lei Zhang, Mingyang Zhao, Lihua Zhao

XML-Based Reconfigurable Measurement System
Hong Lai, Lingsong He

Research on 3D Visual Space Distortion in a Rotational-Stereo Micro Measurement System
Sheng Liu, Yan Yu, Shengchun Long

Research on Virtual NC Technique in Turning and Milling Process
Lida Zhu

The Online Monitoring System of Tool Wear in Numerical Control Plunge Milling Based on PC104 Bus
Jianjun Sun, Pingyu Zhu, Xiaoyu Li, Huanling Liu, Zhixing Yuan, Xuda Qin

**SU-P11: Modeling and Simulation I**

A New Lattice Model for Traffic Flow and Its Analysis
Wenxing Zhu

Multi-Fractal Local Singularity Research of Power Load Time Series
Min Zhao, Yinhai Fan, Nan Qiu

Modeling and Simulating of Spiral Bevel Gears Based on Actual Cutting Process
Zhaowen Li, Yong Wang, Deyu Xue

Modelling of Large Ship Motion and Design of Intelligent Rudder Control Mechanism
Yuanhuai Wang, Xiaocheng Shi, Guoqing Xie, Bian Xinliang

Maximum Adhesion Force Control Simulated Model of Electric Locomotive
Wenli Lin, Zhigang Liu, Lijun Diao, Gang Zhang, Dan Chen, Zhefeng Li
SU-E1: System Identification II

A Semi-blind Method for MIMO channel identification
Mengxing Li, Zemin Liu, Longyang Hunag, Weimin Zuo

Recognizing the Patterns of Wood Inner Defects Based on Wavelet Neural Networks
Lihai Wang, Qi Wei, Jinzhuo Wu, Weiping Hou

Parameter Identification for Wiener Model Using Particle Swarm Optimization with a Case Study
Yan Zhang, Shaoyuan Li

Finding Discordant Subsequence in Multivariate Time Series
Xiaoqing Wang, Junyi Shen

Study on Identification Method for Urban Road Traffic Conditions with Inductive Loop Data
Hailong Guo, Gуйyan Jiang, Weigang Zhu

Nonlinear System Identification Based on Genetic Algorithm and Grey Function
Zhelong Wang, Hong Gu

SU-E2: Control System Design

An LMI Approach to D-stable Robust H∞ Fault tolerant Control of Uncertain systems
Jun Li, Gang Wu, Zhiquan Wang

Linear Motor Driven Inverted Pendulum And LQR Controller Design
Xianmin Chen, Huixing Zhou, Ronghua Ma, Fuchang Zuo, Guofang Zhai, Minli Gong

Design of Variable Structure Control for Uncertain Neutral Delay Systems
Youguo He, Yuanwei Jing, Gang Dong, Ningfeng Jing

Nonlinear Control Based on Integral Sliding Surfaces
Daozheng Liao, Renming Wang, Jianshu Hou

Fuzzy-Based Hybrid Control for Nonlinear Multivariable System
Zhenlei Wang, Peng Qian, Rongbin Qi

Modeling and Hover Control of a Novel Coaxial Rotor/Ducted-Fan Helicopter
Hongqiang Wang, Daobo Wang, Xinwen Niu, Haibin Duan

SU-E3: Algorithm Optimization I

Evaluation of Loading Based Toll Station Operation Using Simulation
Wen Hang, Ke Tang, Yong Zhang, Zhiguo Qi

Bidding-Evaluation of Construction Projects Based on VIKOR Method
Hongyan Liu, Yan Tao

Order Form Selection and Evaluation Model based on Particle Swarm Optimization(PSO) for Task Holon
Fuqing Zhao, Qiuyu Zhang, Yahong Yang

An Optimal Two-stage Algorithm for Slab Design Problem with Flexible Demands
Tieke Li, Xi Yang

Algorithm of Fast Marriage in Honey Bees Optimization and Convergence Analysis
Chenguang Yang, Jie Chen, Xu-yan Tu

Method for Solving a System of Fuzzy Equations based on metric and allowable uncertainty
Chenxia Jin, Zhanjing Wang, Fachao Li

SU-E4: Logistics Strategy I

A Flexible Solution Framework for Optimal Decision in Logistics Systems
Pan Zhang, Lei Jia, Guohui Tian, Xiaolei Li
A Theoretical Framework of an Integrated Logistics System for UK Construction Industry
Lei Liu, Panagiotis Georgakis, Christopher Nwagboro

Quality Evaluation on Manufacturing Enterprise's Logistics System
Decheng Wen, Gaoshan Wang

Empirical Analysis on Spread Characteristic and Economic Contribution of China's Logistics Industry
Ming Zhong, Ningbo Jiao, Guosong Chang

Study on the Evaluation Model of the 3rd Party Logistic Provider Based on Rough Sets and Support Vector Machine
Yingchun Zhong, Yinghong Zhong

Study on the Relation of Local Railroad Freight Transportation and Region Economic Growth
Hanli Chen, Feilian Zhang, Tao Qin

SU-E5: Supply Chain Management III
A Research on the Renewable Resources' Utilization for Reverse Supply Chain
Ying Gong, Jingwei Tang

A Review and Analysis of Researches on Supply Chain Partnership
Quanxi Li, Yong Su, Yilei Pei

Multi-objective Optimization Algorithm Analysis on Supply Chain Resources Integration Decision in Liwen Liu, Jianming Yao

Perishable Products' Supply Chain Coordination with Option Contract under Two-Period Production Mode
Xiyu Cao, Zeyou Yao, Ronghua Lu

Research on Collaborative Production Planning and Scheduling of Dynamic Alliance
Meihua Zhang, Aliping Li, Liyun Xu

Game Theoretical Framework for Process Plan Decision of Jobs in Networked Manufacturing
Guanghui Zhou, Pingyu Jiang, Guohui Zhang

SU-E6: Vehicle Routing Optimization I
Research on VRPTW of Optimizing Based on Fuzzy c-means Clustering and IGA under Electronic Commerce
Chunyu Ren

A Compound PRM Method for Path Planning of the Tractor-trailer Mobile Robot
Fengchi Sun, Fengying Ma, Yalou Huang, Jing Yuan, Yewei Kang

A New Fast Border Search Algorithm and Its Expansion
Haichao Zhang, Guifang Wu, Xiuming Sun, Jinwu Xu, Ke Xu

Study on Supplier’s Quality Supplying Competence Index in the Case of Multi-quality Characteristics without Excursion
Decheng Wen, Kaipeng Li, Gaoshan Wang

The Assignment of Customers in Multi-depot Vehicle Routing Problem with Fleet Size Constraint for Each Depot
Canrong Zhang, Zhihai Zhang, Zheng Li, Linming Cai

Ant Colony System Algorithm for Path Routing of Urban Traffic Vehicles
Jingyu Liu, Yanjun Feng, Yijian Liu

SU-E7: Image Processing I
Photometric Match for Seamless Tiled Display Wall
Xihuai Wang, Junqin Wen, Huijuan Lu

Local Linear Embedding based on Image Euclidean Distance
Lijing Zhang, Ning Wang
Automatic Alignment of Images with Small Overlaps, Sparse Features and Repeated Deceptive Objects
Ran Song, John Szymanski

A Color Image Segmentation Method Based on Automatic Seeded Region Growing
Weiwei Li, Huxian Huang, Dongbo Zhang, Hongzhong Tang, Chenhao Wang

A Single-Hand and Binocular Visual System for EOD Robot
Luqiao Fan, Xifan Yao, Hengnian Qi, Liangzhong Jiang, Wei Wang

A Novel Image Fusion Algorithm Based on IHS and Discrete Wavelet Transform
Yi Yang, Chongzhao Han, Xin Kang, Deqiang Han

SU-E8: Robot Control I

Architectural Proposal for a Robotized Intelligent Humanoid, Iziman
Nizar Rokbani, Mohamed Adel Alimi, Boudour Ammar

A New Solution for Inverse Kinematics of 7-DOF Manipulator Based on Genetic Algorithm
Yugui Yang, Guangzheng Peng, Yifeng Wang, Hongli Zhang

FastSLAM and Its Data Association Approaches for Mobile Robots
Lijin Guo, Huaxiang Wang, Qinghao Meng, Yanan Qiu

A New Solution for Inverse Kinematics of 7-DOF Manipulator Based on Neural Network
Yugui Yang, Guangzheng Peng, Yifeng Wang, Hongli Zhang

Practical Algorithm for Solving Real Time Inverse Kinematics of Industrial 7R Robot
Pin Wang, Dong Li, Di Zhang, Kening Liu, Shaoxin Zheng

A New Gradient Annealing Algorithm (GAA) and its Applications in Path Planning of Mobile Robot
Zhongmin Wang, Yi Dai

A Mobile Robot Localization Method Based on Radio Interference
Zhiguang Zhong

SU-E9: Networked Systems I

ZigBee Based Wireless Sensor Networks and Its Applications in Industrial
Shizhuang Lin, Jingyu Liu, Yanjun Fang

Optimum Arrangement Scheme of PMU and Voltage Stability Evaluation in Region Electric Network
Weifu Qi, Honglei Yang, Jianyuan Xu

Robust H∞ Controller of Tubular Linear Induction Motor with an Artificial Neural Network Compensator
Qing Hu, Jiao Wang, Dongmei Yu, Jiefan Cui

Location Algorithms Research in Wireless Sensor Network Base on Hops and Angle-Vector
Zhenhua Wei, Shaodong Ji, Changan Liu

Research of Remote Real Time Monitor System for Electromechanical Equipments Based on Internet
Ruzhong Yan, Lijing Lu

On the Resource Allocation for Wireless and Hoc Networks
Yi Chen, Ge Gao, Ruimin Hu

SU-E10: Motion Control I

Maximum Output Power Control of Permanent Magnet Synchronous Motor Based on Energy-shaping Principle
Haisheng Yu, Jun Hou, Yong Wang

Sensorless Speed Estimation for Line-connected Induction Motor Based on Recurrent Multilayer Neural Network
Jing Yang, Liguo Wang, Dianguo Xu, Bing Xue
Magnetic Field Analysis of a Halbach Array PM Spherical Motor
Hongfeng Li, Changliang Xia, Peng Song, Tingna Shi 2019

Research on the Automatic Frequency Modulation of Rubidium Frequency Standard
Yutai Wang, Feng Liu, Jie Sun 2024

Neural Network Self-adaptive PID Control for Driving and Regenerative Braking of Electric Vehicle
Jianbo Cao, Binggang Cao, Wenzhi Chen, Peng Xu 2029

State-Predicted-Based DTC-SVM of Induction Machine with Improved Torque Performance
Pinghua Zhang, Guijie Yang 2035

SU-E11: Modeling and Simulation II
HLA Based High Level Modeling and Simulation for Integrated Logistical Supporting System
Xin Xu, Wenhui Fan, Yuming Yuan, Bin Guo, Junhai Cao, Wei Wang 2041

A Novel Modeling Design Method for Automated Storage and Retrieval System Based on Petri Nets
Xiaowei Xu, Zhiyan Wang, Yanyan Wang, Xiaoye Cao, Yinghong Liang, Yaohua Wu 2046

Storage & Transportation Scheduling Model and Algorithm of Petroleum Products Based on Network
Xiaoqiang Zhao, Wei Li, Yan Wan 2052

Proportional Production Research for Machining-center Based on Multi-Agent
Meixian Jiang, Shousong Jin, Zhenxiang Yao, Qiuxiang Xiong, Dingzhong Peng 2056

Modeling and Simulation for Joint Operation Materiel Support System
Yanzhong Zhang, Yongli Yu, Liu Zhang, Chenglong Nie, Changzheng Qu 2061

Fuzzy Optimization Design and Motion Simulation
Xianhai Yang, Wang Wang 2066

MO-A1: System Identification III
A Bran-new Feature Extraction Method and its Application to Surface Defect Recognition of Hot Rolled Strips
Guifang Wu, Haichao Zhang, Xiuming Sun, Jinwu Xu, Ke Xu 2069

L2-Linf Norm of Polytopic Systems with Time-varying Delay
Qingyang Wang, Qing Wang, Hailong Pei 2075

A Reliability Prediction Method Adapting to Informationization Materiel System
Shiying Li, Yongli Yu, Chenglong Nie, Huijuan Feng, Le Chen 2080

The Design of Position Estimator for PMSM by Using Diagonal Recurrent Neural Network
Fanjin Sun, Xinxiang Pan, Yancheng Liu 2084

Hierarchical Least-squares Identification of Transfer Function and Application on Platform System
Xinliang Pang, Daoping Fan, Lianchao Zhang, Hua-zheng Zhu 2089

Equipment Fault Forecasting Based on a Two-level Hierarchical Model
Xiaoling Bian, Quanzhi Xu, Bo Li, Limei Xu 2095

MO-A2: Fuzzy and Neural Systems
Fuzzy T-S Modeling and Fuzzy Control Research on Networked Control Systems
Guimei Cui, Zhichun Mu, Xiaoli Li, Huling Mu 2100

Delay-Dependent Generalized H2 Resilient Control for Discrete-Time Fuzzy Systems with both State and Input Delays
Zhile Xia, Junmin Li, Jiarong Li 2105

Adaptive Backstepping Control of Servo Systems Using Self-Recurent Wavelet Neural Networks
Jinzhu Zhou, Baoyan Duan, Jin Huang 2111

Performance Enhancement of Multiple Model Adaptive Control by Using Neural Networks
Xiaoli Li, Yan Zhang, Xiaolong Qian 2117
<table>
<thead>
<tr>
<th>Title</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Adaptive Fuzzy Control Technology for Automatic Oil Drilling System</td>
<td>2123</td>
</tr>
<tr>
<td>Qingjie Zhao, Fasheng Wang, Wei Wang, Hongbin Deng</td>
<td></td>
</tr>
<tr>
<td>Exponential Stability of Bidirectional Associative Memory Neural Networks with Delays and Impulsive</td>
<td>2128</td>
</tr>
<tr>
<td>Chaolong Zhang, Fengjian Yang, Wei Li, Dongqing Wu</td>
<td></td>
</tr>
<tr>
<td><strong>MO-A3: Algorithm Optimization II</strong></td>
<td></td>
</tr>
<tr>
<td>Research of Enhancing Smooth Degree of data sequence Based on Genetic Algorithm and Its Application</td>
<td>2133</td>
</tr>
<tr>
<td>Junfeng Li, Aiping Yang, Wenzhan Dai</td>
<td></td>
</tr>
<tr>
<td>Multiple Classifiers Fusion Based on Weighted Evidence Combination</td>
<td>2138</td>
</tr>
<tr>
<td>Deqiang Han, Chongzhao Han, Yi Yang</td>
<td></td>
</tr>
<tr>
<td>Fast Genetic Algorithms used for PID Parameter Optimization</td>
<td>2144</td>
</tr>
<tr>
<td>Xiangzhong Meng, Baoye Song</td>
<td></td>
</tr>
<tr>
<td>Dynamic Traffic Assignment Model and Solution under Close-loop Information Structure</td>
<td>2149</td>
</tr>
<tr>
<td>Qiaoru Li, Liang Chen, Lianyu Wei, Shoufeng Ma</td>
<td></td>
</tr>
<tr>
<td>Multiple K-NN Classifiers Fusion Based on Evidence Theory</td>
<td>2155</td>
</tr>
<tr>
<td>Deqiang Han, Chongzhao Han, Yi Yang</td>
<td></td>
</tr>
<tr>
<td>Research on Acceleration Performance Indices for Serial Mechanism</td>
<td>2160</td>
</tr>
<tr>
<td>Qingxia Geng, Han Lingling, Xijuan Guo</td>
<td></td>
</tr>
<tr>
<td><strong>MO-A4: Logistics Strategy II</strong></td>
<td></td>
</tr>
<tr>
<td>Study on The Mechanism of Logistics System Sustainability</td>
<td>2165</td>
</tr>
<tr>
<td>Jiru Wang, Daohong Zhang</td>
<td></td>
</tr>
<tr>
<td>An Optimization Model and Its Solution Algorithm for Distribution Network Design Problem with Uncertainty Demand</td>
<td>2170</td>
</tr>
<tr>
<td>Zhiya Chen, Shuangyan Li, Dezhi Zhang</td>
<td></td>
</tr>
<tr>
<td>Service Time and Price Decisions under Port Competition and Cooperation</td>
<td>2176</td>
</tr>
<tr>
<td>Chuanxu Wang, Liangkui Jiang</td>
<td></td>
</tr>
<tr>
<td>Pricing Decision for Two Differentiated Products</td>
<td>2181</td>
</tr>
<tr>
<td>Jie Wei, Jing Zhao</td>
<td></td>
</tr>
<tr>
<td>Research on an optimization model for logistics nodes dynamic location and its solution algorithm</td>
<td>2187</td>
</tr>
<tr>
<td>Dezhi Zhang, Ruhe Xie, Ting Liu, Shuangyan Li</td>
<td></td>
</tr>
<tr>
<td>An Extended Analysis of Consignment Stock Policy in the Presence of Product Obsolescence</td>
<td>2193</td>
</tr>
<tr>
<td>Lienen Liu, Yunfei Sun, Jianming Yao</td>
<td></td>
</tr>
<tr>
<td><strong>MO-A5: Supply Chain Management IV</strong></td>
<td></td>
</tr>
<tr>
<td>Study on Dynamic Management of Military Logistics System Core Competence</td>
<td>2199</td>
</tr>
<tr>
<td>Baofeng Li, Darong Ling</td>
<td></td>
</tr>
<tr>
<td>Fuzzy Bi-Level Multi-Objective Programming for Supply Chain</td>
<td>2203</td>
</tr>
<tr>
<td>Ying Li, Shalin Yang</td>
<td></td>
</tr>
<tr>
<td>Research of Co-competition Evolutionary of Supply Chain Networks Based on Penalties and Bonuses Incentive Mechanism</td>
<td>2208</td>
</tr>
<tr>
<td>Haisheng Yu, Lindu Zhao, Yinghong Long</td>
<td></td>
</tr>
<tr>
<td>The Design of Supply Chain Collaboration Base on RosettaNet Standards</td>
<td>2212</td>
</tr>
<tr>
<td>Shi Jing, Xiuquan Chen</td>
<td></td>
</tr>
<tr>
<td>Feng Yi, Nan Liu, Mingrong Deng</td>
<td></td>
</tr>
</tbody>
</table>
MO-A6: Vehicle Routing Optimization II

A Column Generation for Locomotive Scheduling Problem in Molten Iron Transportation
Gongshu Wang, Lixin Tang

Solving the Traveling Salesman Problem Using Elastic Net Integrate with SOM
Jingjie Chen, Jiusheng Chen, Xiaoyu Zhang

A hybrid Algorithm for Large-Scale Vehicle Routing Problem in Real Traffic Condition
Hua Zeng, Yaohua Wu, Danyu Zhang, Jing Li

A Container Vehicle Routing Model with Variable Traveling Time
Shengqiang Wen, Pengfei Zhou

Multi-objective Path Planning for the Mobile Robot
Caihong Li, Yibin Li, Fengyu Zhou, Fan Chen

A Hybrid Genetic Algorithm for the Multiple Depot Capacitated Arc Routing Problem
Zhengyu Zhu, Xiaohua Li

MO-A7: Image Processing II

Detection of Cracks in Computer Tomography Images of Logs Based on Fractal Dimension
Li Li, Dawei Qi

User Interest Model-based Image Retrieval technique
Jianhua Li, Mingsheng Liu, Yan Cheng

Fast Mosaic of High-Resolution Multiple-View Images of Surfaces from Architectural and Heritage Structures
Ran Song, John Szymanski

Image Denoising Based on Multiple Wavelet Representations and Universal Hidden Markov Tree
Wei Zhang, Qingmei Sui, Weihua Liu, Qi Jiang

Medical Image Edge Detection Based on Omni-directional Multi-Scale Structure Element of Mathematical Morphology
Dawei Qi, Fan Guo, Lei Yu

Study on the Safety of Wall Robot Based on Redundant Control
Taiyong Wang, Ai fen Xu

MO-A8: Robot Control II

A Novel Speed Control Algorithm with Programmable Timer for Embedded Motion Control System
Baoren Wang, Lei Jia, Daguang Shi, Chengrui Zhang, Hong'en Wu

Simulation Study on Searching for Food by Cooperation of Multi-Robots with Swarm Intelligence
Lan Wang, Qian Zhang, Nianfeng Wan

Research on Master-Slave Robots Bilateral Control Strategy with Force Tele-Presence
Tiehua Chen, Dingxuan Zhao, Zhuxin Zhang

An Algorithm of Acquisition for Diagnostic Parameters of Engine Fault Based on Fuzzy-Rough Sets
Yunxue Song, Yongsheng Shi, Chuanchao Zhang

A New Algorithm for Mobile Robot Obstacle Avoidance Based on Hydrodynamics
Changan Liu, Zhenhua Wei, Chunyang Liu

Dynamic Surface Control for Hypersonic Aircraft Using Fuzzy Logic System
Daoxiang Gao, Zengqi Sun, Tianrong Du
MO-A9: Networked Systems II

Fault Detection Based on the States Observer for Networked Control Systems with Uncertain Long Time-Delay
Zhangqing Zhu, Xianzhong Zhou

A Fusion Algorithm of Multisensor System Based on Sequential Filtering in Distributed Network
Xiaobin Xu, Quanbo Ge, Chenglin Wen

Optimal Tasks and Messages Scheduling for Asynchronous Networked Control Systems
Ning Liu, Huai Liu, Shumin Fei

Fault Diagnosis of Distributed Networked Control Systems
Qun Zong, Renjiang Liu, Liankun Sun

An Overview on Pixel-Level Image Fusion in Remote Sensing
Yi Yang, Chongzhao Han, Xin Kang, Deqiang Han

A Novel MAC Protocol for Hidden Receiver Problem in Ad Hoc Networks
Lihong Dong, Yan'an Jin

MO-A10: Motion Control II

A New Variable Structure Controller for Direct Torque Controlled Interior Permanent Magnet Synchronous Motor Drive
Yeyao He, Wen Jiang

A Synchronous Drive Control Scheme Based on Neural Networks for a Novel XY-table
Jing Chen, Liu Qiang, Qi Chang

Velocity Control for Rope-less Elevator Using Permanent Magnet Linear Synchronous Motor with Adaptive Fuzzy PID
Qing Hu, Jing Zhang, Dongmei Yu, Jiefan Cui

Adaptive Inverse Induction Machine Control Based on Variable Learning Rate BP Algorithm
Shuying Xie, Chengjin Zhang, Xiangli Xiao

Research on Turtle Hydrofoil Motion Principle and Bionics
Dinghui Chu, Xiaobai Liu, Mingjun Zhang

Iterative Learning Control for Linear Motor Motion System
Liping Fan, Yi Liu

MO-A11: Modeling and Simulation III

Modeling and Simulation of Big Deformations of Thin walled Plate in End Milling Process
Aijun Li, Zhanqiang Liu, Hailong Ma

Study on the Asymmetric Information Problems in Knowledge Alliance
Jun Luo, Weiguo Zhang, Bingshan Wu

Dynamic Analysis and Design of the Spindle-Bearing System in Turn-milling Centre
Lida Zhu

An Adaptive Particle Swarm Optimization Algorithm and Simulation
Dingxue Zhang, Zhihong Guan, Xinzhi Liu

A Design of Quadruped Based CPG and Fussy Neural Network
Lei Sun

Research on Medicine E-business Platform Model Based on Value-chain and Value-Net Theory
Qinghua Zhang

MO-P1: System Simulation I

Study on Construction of Simulation Platform for Vessel Automatic Anti-collision and Its Test Method
Shenhua Yang, Lina Li, Yongfeng Suo, Guoquan Chen
Analysis on Random-like Property of Chaotic Motion With Exhaustive Entropy 2420

Mingkuo Feng, Shuisheng Qiu, Xiongying Liu, Jianxiu Jin

Hardware-in-the-loop Simulation Approach to Testing Controller of Sequential Turbocharging System 2426

Jianwei Du, Yingyan Wang, Chuanlei Yang, Hechun Wang

A Simulation Method of Controlled Hybrid Petri Nets Based on Matlab Simulink/Stateflow 2432

Jinsong Zhang, Qiqiang Li, Zhaoxia Wang, Qingqiang Guo

Traffic Network Equilibrium Simulation Based on Multi-Agent 2437

Jianghua Zhang, Xiaoping Zheng, Bing Xu, Liyan Cai

Research on Parameter Matching of Front Axle Suspension Vehicle Based on MATLAB 2441

Baozhan Lv, Sihong Zhu, Ying Zhang

MO-P2: Control Design I

Research on Nonlinear PID Position Controller of CNC System 2446

Guoyong Zhao, Yuyang Zhao, Aimei Dong, Lili Zhang

Decentralized Controller Design for String of Moving Vehicles Based on Inclusion Principle 2451

Lianzeng Ma, Xuebo Chen

Robust Guidance Design Based on Guaranteed Cost Control 2456

Hongmei Zhang, Guoshan Zhang

Proportional and Differential Control of a Nonlinear Capacitor Chaos Circuit 2462

Xuemei Wang, Bo Zhang

Neuro-PID Control of Hybrid Machines With 2-DOF for Trajectory Tracking Problems 2467

Zhenghong Chen, Yong Wang, Yan Li

Design of Optimal Tracking Controller for Systems with Control-Affine Form 2472

Yandong Zhao, Xianli Chen

MO-P3: Algorithm Optimization III

Restricted Searching Area Route Guidance Based on Neural Network and EA 2477

Zhonghua Han, Chengdong Wu, Bin Me, Jiejia Li, Ke Xu

An Improved Hybrid Genetic Algorithm for Solving Multi-modal Function Global Optimization Problem 2486

Dahai Zhang, Qijuan Chen, Jingyu Liu

An Improved Hybrid Genetic Algorithm for Solving Multi-modal Function Global Optimization Problem 2486

Dahai Zhang, Qijuan Chen, Jingyu Liu

Research and Implementation of time Synchronization Algorithm based on Frequency Adjustment in Distributed System 2490

Peng He, Bin Zhao, Bijing Wang, Yi Na

Optimal Route Selection Method Based on Grey Incidence Analysis 2495

Yan Sun, Yi Wu, Zheng Sun

A Hybrid Prognostics Method for On-line Performance Assessment and Remaining Life Prediction in Drilling Operations 2500

Jihong Yan, Jay Lee

MO-P4: Logistics Strategy III

Evaluation of Operational Performance of Third-party Logistics: Based on the Merger Theory Model of Integration and Specialization 2506

Lidong Wang, Nan Liu

Research on Interaction Mechanism of Regional Logistics Nodes 2510

Feng Wang, Xiaoyan Cui, Xuhong Li, Haijun Mao
<table>
<thead>
<tr>
<th>Title</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>The Application of Association Rules in Retail Marketing Mix</td>
<td>2514</td>
</tr>
<tr>
<td>Hongwei Liu, Bin Su, Bixi Zhang</td>
<td></td>
</tr>
<tr>
<td>Research on Green Technical Services system Oriented Product Lifecycle</td>
<td>2518</td>
</tr>
<tr>
<td>Tianbiao Yu, Zixu Liu, Jing Zhou, Yadong Gong, Wanshan Wang</td>
<td></td>
</tr>
<tr>
<td>Reverse Logistics System Planning for Recycling Waste Household Electrical Appliances in Liaoning Province</td>
<td>2524</td>
</tr>
<tr>
<td>Tong Zhao, Yan Liu, Houming Fan, Jili Ci</td>
<td></td>
</tr>
<tr>
<td>Methodology of Building Integrated Platform for Logistics Planning</td>
<td>2530</td>
</tr>
<tr>
<td>Xiangdong Hu, Dongyang An, Ping Cui, Huling Cao</td>
<td></td>
</tr>
<tr>
<td><strong>MO-P5: Supply Chain Performance Evaluation I</strong></td>
<td></td>
</tr>
<tr>
<td>Optimize E-Commerce Supply Chain Based on the Fuzzy Clustering Analysis</td>
<td>2535</td>
</tr>
<tr>
<td>Wanhuo Meng</td>
<td></td>
</tr>
<tr>
<td>A Hybrid Method for Improving Agent-based Negotiation Efficiency in Supply Chain</td>
<td>2540</td>
</tr>
<tr>
<td>Xiaolong Xue, Yaowu Wang, Qiping Shen</td>
<td></td>
</tr>
<tr>
<td>The Framework of Supply Chain Coordination Mechanism Choice: A View of Transactions Cost</td>
<td>2544</td>
</tr>
<tr>
<td>Daozhi Zhao, Longfei He, Yanli Wang</td>
<td></td>
</tr>
<tr>
<td>The Strategy of Harmonize and Optimize Their Supply Chain Management under Mass Customization</td>
<td>2550</td>
</tr>
<tr>
<td>Jiuhu Wang, Fan Yan, Xiaoxia Li</td>
<td></td>
</tr>
<tr>
<td>Modeling and Analysis of Supply Chain System for MTO Production based on GSPN Approach</td>
<td>2555</td>
</tr>
<tr>
<td>Zengzhi Ma, Longshan Wang, Hong Gao</td>
<td></td>
</tr>
<tr>
<td>Hybrid Petri Net Based Modelling and Simulation of Agile Supply Chain Dynamic Systems</td>
<td>2560</td>
</tr>
<tr>
<td>Wen Wang, Weiping Fu</td>
<td></td>
</tr>
<tr>
<td><strong>MO-P6: Logistics Information Systems</strong></td>
<td></td>
</tr>
<tr>
<td>Research on Manufacturing Resources Collaboration Based on e-HUB Platform</td>
<td>2566</td>
</tr>
<tr>
<td>Qingni Yuan, Qingsheng Xie, Shaobo Li</td>
<td></td>
</tr>
<tr>
<td>The Information Sharing Platform for Port Container Terminal Logistics using Virtual Reality</td>
<td>2570</td>
</tr>
<tr>
<td>Fan Shu, Ziqi Xu</td>
<td></td>
</tr>
<tr>
<td>Study on Cooperative Logistics Information System According to Supply Chain Management</td>
<td>2576</td>
</tr>
<tr>
<td>Linqi Gao, Ershi Qi</td>
<td></td>
</tr>
<tr>
<td>An Improved Nash Equilibrium Algorithm and its Application on Financial Investment</td>
<td>2580</td>
</tr>
<tr>
<td>Guangwen Kong, Daoli Zhu</td>
<td></td>
</tr>
<tr>
<td>Research on the Application of Radio Frequency Identification in Cigarette-Distribution Systems</td>
<td>2586</td>
</tr>
<tr>
<td>Hongchun Hu, Yaohua Wu, Xiaoyu Hu, Li Liao, Na Xu</td>
<td></td>
</tr>
<tr>
<td>Research and Design on Pallet-throughout System Based on RFID</td>
<td>2592</td>
</tr>
<tr>
<td>Shaoping Lu, Yaohua Wu, Yongtao Fu</td>
<td></td>
</tr>
<tr>
<td><strong>MO-P7: Image Processing III</strong></td>
<td></td>
</tr>
<tr>
<td>Camera Calibration Based on Improved Genetic Algorithm</td>
<td>2596</td>
</tr>
<tr>
<td>Yingjie Xing, Qiao Liu, Jing Sun, Long Hu</td>
<td></td>
</tr>
<tr>
<td>A Music-Colors Display System for Weather Conditions</td>
<td>2602</td>
</tr>
<tr>
<td>Zhi Wang, Shaorong Li, Lei Deng, Jun Cheng, Xinyu Wu, Yangsheng Xu</td>
<td></td>
</tr>
<tr>
<td>Color Image Watermarking Algorithm Based on DWT-SVD</td>
<td>2607</td>
</tr>
<tr>
<td>Chenggun Yin, Li Li, Anqiang Lv, Qu Li</td>
<td></td>
</tr>
<tr>
<td>A Novel Approach to Image Roto-translation Estimation</td>
<td>2612</td>
</tr>
<tr>
<td>Li Li, Zhenshen Qu, Qingshuang Zeng, Fanfeng Meng</td>
<td></td>
</tr>
</tbody>
</table>
Wavelet-domain Image Denoising Using Contextual Hidden Markov Tree Model
Yida Ma, Yong Tian, Jiwen Zhang

Selection of Image Features for Robot Vision System
Qingjie Zhao, Hongbin Deng, Wenyao Zhang, Aixia Mu

MO-P8: Robot Control III
Dynamics Modeling and Co-simulation of Rigid-flexible Coupling System of 3-TPT Parallel Robot
Chunxia Zhu, Lida Zhu

Fuzzy PID Control Orienting Medical Robot in Minimally Invasive Surgery
Qinjun Du

Application of Intelligent Control Strategy in Movements of Arm Wrestling Robot
Huanghuan Shen, Xiaohong Deng, Yong Yu, Yunjian Ge

A Topological Area Coverage Algorithm for Indoor Cleaning Robot
Haihong Zhang, Wenzia Wang, Wei Zhao

Mobile Robot Path Planning Based on Q-ANN
Hairong Xiao, Li Liao, Fengyu Zhou

Forward Kinematics of the 6-6 Stewart Platform with Planar Base and Platform Using Algebraic Elimination
Xiguang Huang, Qizheng Liao, Shimin Wei, Shuguang Huang, Qiang Xu

MO-P9: Networked Systems III
Sliding Mode Variable Structure Control of Networked Control System
Laihua Fang, Zongzhi Wu

Remote Intelligent Monitoring System Based on Embedded Internet Technology
Zhen Zhu, Ruchun Cui

Improving Immunity of Colliery Mobile Communication and Gas Monitor to Underground Haulage Motors Electromagnetic Interference
Jiping Sun, Fengying Ma

Reliable and Fast Estimation for Wireless Media RFID Systems
Xu Huang, Dharmendra Sharma

Internet/Ethernet-Based Computer Numerical Control System
Qingrong Ren, Jihong Chen, Xiaoki Tang, Xiangli Zhang

A Nonlinear Predictive Model Based on Multilayer Perceptron Network
Huijun Li, Ji Gang, Zengliang Ma

MO-P10: Motion Control III
Research on the Control System of Linear Motor Driving Using Wavelet Transform
Yingfeng Chen, Changjiu Li, Lijun Zhao, Jiefan Cui

Application of Sliding Mode Control Based on Disturbance Observer on High Performance Flight Motion Simulator
Yunjie Wu, Weiling Le, Dapeng Tian

Error Modeling of A New Kind of Plane Movement Position and Attitude Measuring Equipment
Zhigang Xu, Liming Xin, Mingyang Zhao

Research of Variable Structure Control System of Supported Rotor System
Jianfeng Liu, Yong Jiang, Chuanhong Ding

Study on Direct Torque Control of Super High-speed PMSM
Chunyuan Bian, Shuangyan Ren, Liangyu Ma

Design and Implementation of an Cement Kiln Expert System
Shaolin Wang, Dongfeng Yuan
MO-P11: Modeling and Simulation IV

Research of Dynamic Simulation Software in Road Machinery Based on Intelligent and Hybrid Multi-Agent System
Guo Long, Hongli Wang

Modeling and Implementation of a Collaborative Design system Based on ASP Mode
Xiaohong Lu, Zhenyuan Jia, Dixin Liu

ADRC Based Ship Course Controller Design and Simulations
Jiuhong Ruan, Yibin Li

A Novel Method to Restrain the Radial Error Propagation in Self-servowriting in Hard Disk
Xiaogang Zhao, Changsheng Xie, Haiwei Wang

Multiple Models Generalized Predictive Control for Superheated Steam Temperature Based on MLD Model
Lijing Zhang, Yue Zhang, Dongfeng Wang, Daping Xu

Stability and Control Analysis Based on Airship Dynamic Modeling
Yu Liu, Yueming Hu, YiLin Wu

MO-E1: System Simulation II

Simulation of the Control Strategy of Vehicular ASR System under the Circumstance of Simulink
Weida Wang, Nenggen Ding, Xiangyang Xu, Jian Zhang

A Novel Genetic Algorithm Based on Individual Diversity and Gene Diversity Maintaining and Its Simulation
Xiaojun Xing, Qiling Jia, Zhigang Ling, Dongli Yuan

Parameter Simulation and Energy Equation Derivation of Port Container Logistics
Yun Liu, Hongda Shi

Research on the Application of Logistics Simulation Technology in the Facility Layout of Discrete manufacturing Enterprise
Xiaoying Yang, Xiaozhong Ren, Zhiwen Zhang, Feng Lv

From Cross-Section to Scanning Path in Rapid Prototyping
Jibin Zhao, Weijun Liu, Lun Li, Renbo Xia

Simulation of Inverter with Switch Open Faults Based on Switching Function
Bowen Cui

MO-E2: Control Design II

Formations Control Based on Piecewise Smooth Dynamic Framework
Yuqing Chen, Shuanghe Yu, Zi Ma

H∞ Fusion Filter Design in Multi-Sensor Fusion System With State Time-Delays
Qinghua Li, Hongjun Wang, Weihai Zhang, Xuezhen Liu

H∞ Dynamic Output Feedback Control for Singularity Perturbed Systems
Yan Li

Suboptimal H2 Static Output Feedback Control for Singularity Perturbed Systems
Yan Li

Variable Structure Control of Flexible Manipulator Based on Distributed Parameter Model
Xiaotao Cao, Yuanchun Li

Lateral Control Law Design for Helicopter Using Radial Basis Function Neural Network
Jingchao Lu, Qiong Ling, Jianming Zhang

A Study on the Internal Relationship among Smith Predictor, Dahlin Controller & PID
Wei Tang, Mengxiao Wang, Yuyan Chao, Lifeng He, Hidenori Itoh
MO-E3: Algorithm Optimization IV

Application of PSO-based Wavelet Neural Network in Tool Wear Monitoring
Hua Huang, Aiping Li, Xiankun Lin

Sequencing Mixed Model Assembly Lines Based on a Modified Particle Swarm Optimization Multi-objective Algorithm
Qiaoying Dong, Shulin Kan, Ling Qin, Zhihui Huang

Optimizing Fixed Shelf Order-Picking for AS/RS Based on Immune Particle Swarm Optimization Algorithm
Xinnin Zhang, Tao Ma, Xiaoguang Han

A Hybrid Approach for Logistics Center Location Using Discrete Particle Swarm Optimization
Guangyi Chen, Wei Guo, Kaisheng Huang

Electricity Load Forecasting Based on Support Vector Machines and Simulated Annealing Particle Swarm Optimization Algorithm
Jingmin Wang, Yamin Zhou, Xiaoyu Chen

A New Method for Container Code Location
Jianqin Yin, Azeng Cao, Jiping Li

MO-E4: Logistics Strategy IV

Research on Fourth Party Reverse Logistics Based on Nonprofit Organization
Qiong Liu, Jing-jing Ye

Evolution of Regional Port System in Modern Logistics
Yuan Zhao, Peng Liu, Zan Yang

Constructing Enterprise Flexibility Competence on the Basis of Product Platform and Collaborative Product Commerce
Qingzhu Qi, Gangqiang Li

An Agent-based Integrated Negotiation Framework of Material Procurement for Lean Construction Material Delivery
Botao Zhong, Lileyun Ding, Zhenwen Zhang

A Hybrid Sales Forecasting Method Based on Stable Seasonal Pattern Models and BPNN
Jiewei Xiao, Yaohua Wu, Qian Wang, Li Liao, Hongchun Hu

Joint decision problem for inventory control and facility location
Xinhua Li, Jin Qin

MO-E5: Supply Chain Performance Evaluation II

The Materialized Form of Military Supply Chain Management Platform: Transaction Cost Economics Analysis
Xiangru Meng, Shuyun Wang

The Effect of Information-sharing on Inventory in a Two-stage Supply Chain
Zaqie Kong, Guoying Hao

Effect of Business Process Reengineering on Logistics Performance: A Case Study of Taiwan
Chienwen Shen

Asymmetric Demand Information's Impact on Supply Chain Performance
Yihong Hu, Jianghua Zhang, Zui Xu

Simulation and Performance Analysis
Tang Da, Li Ye

The Impact of Information Sharing Pattern and Replanning Cycle on the Performance of Supply Chain
Huiying Zhang, Puqing Wu, Xiande Zhao, Jeff Yeung
MO-E6: EPC and RFID

Warehouse Logistics Control and Management System Based on RFID
Xiaojin Lian, Xiaoli Zhang, Yifang Weng, Zhengang Duan

Design for UHF RFID Reader and Selection for Key Parts
Xiaohua Wang, Xueguang Zhou, Baisheng Sun

RFID Anti-collision algorithm Based on Bi-directional Binary Exponential Index
Songsen Yu, Yiju Zhan, Yonghua Wang

A RFID-based Material Tracking Information System
Min Zhang, Wenfeng Li, Zhongyun Wang, Bin Li, Xia Ran

The Application of Radio Frequency Identification Technology on Tires Tracking
Yanyan Wang

Apply Model Integration in RFID Technology Adoption Analysis
Zongwei Luo, Kwok Chow, Edward Wong, CJ Tan

MO-E7: Computer Vision and Recognition

Camera Calibration Method in Reverse Engineering
Qijuan Lv, Genliang Hou, Ziming Luo

3D Reconstruction of Body of Revolution’s Curved Surface from CCD Image Based on Fictitious Dimensional Plane and Available in Vision measurement
Yingjie Xing, Long Hu, Jing Sun, Zhentong Chen

Vector Silhouette Extraction for Generating Blueprint
Xuemei Lu, SungJong Eun, TaekKeun Whangbo

A Robust and Fast Motion Segmentation method for Video Sequences
Yinghong Liang, Sen Guo, Yangqing Zhang, Xiaowei Xu, Xiaoye Cao

Robust Vehicle Detection in Vision Systems Based on Fast Wavelet Transform and Texture Analysis
Peiqun Lin, Jianmin Xu, Jianyong Bian

License Plate Recognition Based on Prior Knowledge
Qian Gao, Xinnian Wang, Gongfu Xie

An Embedding Method in Image Based on vVisual Redundancy
Xiaoyan Qiao, Guangrong Ji, Liang Hui

MO-E8: Robot Control IV

Development of Underwater Robot Hand and Its Finger Tracking Control
Hua Wang, Xiaodiao Huang, Xindan Qi, Qingxin Meng

Performance Evaluation of a Two Degree of Freedom Micro Parallel Robot
Sergiu Dan Stan, Radu Balan, Vistrian Maties

Mobile Robot Behavior Controller Based on Genetic Diagonal Recurrent Neural Network
Yanchun Du, Yibin Li, Guiyu Wang

Motion Planning Algorithm for Heterogeneous Combinatorial Robots in Time-Varying Environment
Hongfa Ho, Wenxiong Liao

Real-Time Robot Joint Variable Extraction from a Laser Scanner
Ali Haghighat Kashani, William Owen, Peter Lawrence, Robert Hall

Analysis of Pushing Manipulation by Humanoid Robot BHR-2 During Dynamic Walking
Tao Xiao, Min Li, Qiang Huang, Weimin Zhang, Le He

MO-E9: Networked Systems IV

Stabilization of networked control systems with both time delay and packet dropout — Part I
HongBo Li, ZengQi Sun, Mo-Yuen Chow, HuaPing Liu, Badong Chen
<table>
<thead>
<tr>
<th>Title</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Stabilization of Networked Control Systems with Both Time Delay and Packet Dropout — Part II</td>
<td>3012</td>
</tr>
<tr>
<td>Hongbo Li, Zengqi Sun, Mo-Yuen Chow, Huaping Liu, Badong Chen</td>
<td></td>
</tr>
<tr>
<td>Stability of Constrained Model Predictive Control for Networked Control Systems with Data Packet Dropout</td>
<td>3018</td>
</tr>
<tr>
<td>Zhijun Li, Lifeng Wang, Xihuang Lai, Shaohui Xu</td>
<td></td>
</tr>
<tr>
<td>Research on Optimization Model and Algorithm of Port Cluster System</td>
<td>3024</td>
</tr>
<tr>
<td>Xuejun Feng, Wei Wang, Liupeng Jiang</td>
<td></td>
</tr>
<tr>
<td>Synchronization Control Strategy of Multi-motor System Based on Profibus Network</td>
<td>3029</td>
</tr>
<tr>
<td>Fang He, Weiming Tong, Qiang Wang</td>
<td></td>
</tr>
<tr>
<td>Development of an Internet Soccer Tele-operation system based on Pocket PC</td>
<td>3035</td>
</tr>
<tr>
<td>Yunhui Zheng, Wei Zheng, Ning Xi, Yuechao Wang</td>
<td></td>
</tr>
</tbody>
</table>

**MO-E10: Motion Control IV**

<table>
<thead>
<tr>
<th>Title</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Parameter Identification of LuGre Tire Model for the Simplified Motion Dynamics of a Quarter-vehicle Model Based on Ant Colony Algorithm</td>
<td>3039</td>
</tr>
<tr>
<td>Jiapeng Han, Yongli Sun, Yanyang Wang</td>
<td></td>
</tr>
<tr>
<td>Fault Diagnosis of Electro-hydraulic Position Servo Closed-loop System Based on Support Vector Regression</td>
<td>3044</td>
</tr>
<tr>
<td>Keqiang Cao, Jianbang Zhang, Liangmou Hu</td>
<td></td>
</tr>
<tr>
<td>Common-grounded BLDCM Drive System Based on FPGA</td>
<td>3050</td>
</tr>
<tr>
<td>Pinghua Tang, Tiecai Li</td>
<td></td>
</tr>
<tr>
<td>Application of LabVIEW to Automated Measuring Dynamic Balancing of Motorcycle Crankshaft</td>
<td>3055</td>
</tr>
<tr>
<td>Yali Zhang, Qiaoshuo Shi, Yanhui Han</td>
<td></td>
</tr>
<tr>
<td>Sensorless DTC of Super High-speed PMSM</td>
<td>3060</td>
</tr>
<tr>
<td>Chunyuan Bian, Shuangyan Ren, Liangyu Ma</td>
<td></td>
</tr>
<tr>
<td>Saturation Compensation Control of Induction Motors Using Adaptive Neural Networks</td>
<td>3065</td>
</tr>
<tr>
<td>Min Fang, Yong Zhang, Zhonghua Wang, Fang Hui, Qianhong Wang</td>
<td></td>
</tr>
<tr>
<td>Unit Sizing of a Stand-alone Hybrid Power System Using Particle Swarm Optimization</td>
<td>3107</td>
</tr>
<tr>
<td>S.M. Hakimi, S.M.M. Tafreshi, A. Kashefi</td>
<td></td>
</tr>
</tbody>
</table>

**MO-E11: Optimization and Algorithms**

<table>
<thead>
<tr>
<th>Title</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Arrival and Departure Lines of Passenger Traffic Special Line Optimization Study</td>
<td>3070</td>
</tr>
<tr>
<td>Xiaosong Xie, Qiliang Ren, Yong Zhou</td>
<td></td>
</tr>
<tr>
<td>Configure and Parameters Optimization for Sheet Metal Flexible Manufacturing System Based on Simulation</td>
<td>3074</td>
</tr>
<tr>
<td>Chun Su</td>
<td></td>
</tr>
<tr>
<td>A Two-Stage Genetic Algorithm for Large-Size Scheduling Problem</td>
<td>3078</td>
</tr>
<tr>
<td>Yongming Wang, Nanfeng Xiao, Hongli Yin, Enliang Hu, Chenggui Zhao, Yanrong Jiang</td>
<td></td>
</tr>
<tr>
<td>Method for Confirming Increasable Bottleneck Device Based on Study of Parallel Operation</td>
<td>3084</td>
</tr>
<tr>
<td>Zhiqiang Xie, Yong Liu, Guangjie Ye, Guangyu Tan</td>
<td></td>
</tr>
<tr>
<td>Scheduling Cross Docking Logistics Optimization Problem with Multiple Inbound Vehicles and One Outbound Vehicle</td>
<td>3089</td>
</tr>
<tr>
<td>Kaiel Song, Feng Chen</td>
<td></td>
</tr>
<tr>
<td>A Hybrid Approach for Course Scheduling Inspired by Die-hard Co-operative Ant Behavior</td>
<td>3095</td>
</tr>
<tr>
<td>Naveed Ejaz, Younus Javed</td>
<td></td>
</tr>
<tr>
<td>A Hybrid Optimization Solution to VRPTW Based on Simulated Annealing</td>
<td>3113</td>
</tr>
<tr>
<td>Yiqing Zhong, Xiao Pan</td>
<td></td>
</tr>
</tbody>
</table>