# TABLE OF CONTENTS

## Volume 1

<table>
<thead>
<tr>
<th>Title</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Reduced Inertial Sensor System (RISS)/GPS Integration Using Particle Filtering for Land Vehicles</td>
<td>1</td>
</tr>
<tr>
<td>Jacques Georgy, Umar Iqbal, Mohamed Bayoumi, Aboelmagd Noureldin</td>
<td></td>
</tr>
<tr>
<td>On-line Tuning of an Extended Kalman Filter for INS/GPS Navigation Applications</td>
<td>9</td>
</tr>
<tr>
<td>Chris Goodall, Naser El-Sheimy, Zainab Syed</td>
<td></td>
</tr>
<tr>
<td>Flight Testing and Data Evaluation of MEMS INS-GPS Hybridisation Filters - First Results</td>
<td>19</td>
</tr>
<tr>
<td>Meiko Steen, Per Martin, Schachtebeck, Rene Plate, Peter Hecker, Stephane Monrocq</td>
<td></td>
</tr>
<tr>
<td>Development of a Frequency Response INS/GPS System Model Based on LSSA for Bridging GPS Outage</td>
<td>28</td>
</tr>
<tr>
<td>Mohammed El-Diasty, Spiros Pagiatakis</td>
<td></td>
</tr>
<tr>
<td>Cycle Slip Detection and Fixing by MEMS-IMU/GPS Integration for Mobile Environment RTK-GPS</td>
<td>35</td>
</tr>
<tr>
<td>Tomoji Tasaka, Akio Yasuda</td>
<td></td>
</tr>
<tr>
<td>Performance Improvement of Integrated MEMS/GNSS Systems</td>
<td>43</td>
</tr>
<tr>
<td>R.-R. De Boer, V. Calmettes, J.-Y. Tounneret, B. Lesot</td>
<td></td>
</tr>
<tr>
<td>Novel Positioning Algorithms for RFID-Assisted 2D MEMS INS Systems</td>
<td>51</td>
</tr>
<tr>
<td>Ming Zhu</td>
<td></td>
</tr>
<tr>
<td>Host-based Tight-integration of MEMS Dead-Reckoning and GPS</td>
<td>59</td>
</tr>
<tr>
<td>Roberto Zanutta, Frank van Diggelen</td>
<td></td>
</tr>
<tr>
<td>Modeling and Analysis of Measurement Time Synchronization Error in Transfer Alignment</td>
<td>64</td>
</tr>
<tr>
<td>Cheon-Joong Kim, Hyun-Seok Kim, Heung-Won Park</td>
<td></td>
</tr>
<tr>
<td>Wireless Localization and Navigation with the Signal of Opportunity by Exploiting Doppler Frequency</td>
<td>73</td>
</tr>
<tr>
<td>Siva Kumar Balaga, Huilin Xu, Liuqing Yang</td>
<td></td>
</tr>
<tr>
<td>A Model-Aided AHRS for Micro Aerial Vehicle Application</td>
<td>81</td>
</tr>
<tr>
<td>Navid Dadkhah, Bernard Mettler, Demoz Gebre-Egziabher</td>
<td></td>
</tr>
<tr>
<td>Rapid Initialization of SINS for Land Vehicle-based Vertically-launched Missiles</td>
<td>90</td>
</tr>
<tr>
<td>Zhenkai Xu, Yong Li, Chris Rizos, Xiaosu Xu</td>
<td></td>
</tr>
<tr>
<td>Precise Time Transfer and Ranging Experiment using ETS-VIII Satellite</td>
<td>96</td>
</tr>
<tr>
<td>Yasuhiko Takahashi, Fumimaru Nakagawa, Hiroo Kunimori, Jun Amagai, Shigeru Tsuchiya, Ryo Tabuchi, Shin'ichi Hama, Hiroyuki Noda</td>
<td></td>
</tr>
<tr>
<td>Ultra-stable Oscillators: Limits of GNSS Coherent Integration</td>
<td>101</td>
</tr>
<tr>
<td>Pascal O. Gaggero, Daniele Borio</td>
<td></td>
</tr>
<tr>
<td>A Picosecond Accuracy Timing System Based on L1-only GNSS Receivers for a Large Aperture Array Radar</td>
<td>112</td>
</tr>
<tr>
<td>Gustav Stenberg, Tore Lindgren, Jonny Johansson</td>
<td></td>
</tr>
<tr>
<td>Real-time Clock Estimation for Precise Orbit Determination of LEO-Satellites</td>
<td>117</td>
</tr>
<tr>
<td>A. Hauschild, O. Montenbruck</td>
<td></td>
</tr>
<tr>
<td>Precise Timing using a High Sensitivity Receiver in Indoor Environments</td>
<td>126</td>
</tr>
<tr>
<td>E. Anyaegbu, J.P. Bickerstaff, P. Fleming, G. Whitworth</td>
<td></td>
</tr>
<tr>
<td>An ANN Embedded POS Algorithm for a Low Cost MEMS INS/GPS Integrated System</td>
<td>138</td>
</tr>
<tr>
<td>Hsiu-Wen Chang, Chia-Yuan Li</td>
<td></td>
</tr>
</tbody>
</table>
Land-Based Navigation Aiding by Fusion with Airborne Sensory Data ........................................ 150
Taher Hassan, Naser El-Sheimy

GPS/INS Integrity Monitoring using a Modified GPBI Filter Bank ........................................ 157
J. Wendel, O. Meister, R. Monikes

Robust Design for GNSS Integration ................................................................. 164
James L. Farrell

Hybrid Extended Particle Filter (HEPF) for INS/GPS Integrated System .................................. 166
Priyanka Aggarwal

Performance of a Low-cost Real-time Navigation System using Single-frequency GNSS Measurements Combined with Wheel-tick Data ........................................ 176
Ch. Hollenstein, E. Favey, C. Schmid, A. Somieski, D. Ammann,

Integrating Loran and GNSS for Safety of Life Applications ............................................... 187
Benjamin B. Peterson, Sherman C. Lo, Per K. Enge

Incorporating Obstructions in GDOP Mapping Through the use of LiDAR Data ...................... 199
Krista Amolins

A New Method for Electronic Compass Magnetometer Calibration for Improving Azimuth Calculation in Magnetometer/GPS Integrated System ........................................ 209
Hang Guo, Donghyun Kim, Richard Langley, Min Yu, Chengwu Zou, Wenwen Huang

Analysis of Low-cost GPS/INS Integration for Bistatic SAR Experiments ............................ 217
Stefan Knedlik, Junchuan Zhou, Zhen Dai, Ezzaldeen Edwan, Otmar Loffeld

A Comparison of the Performance of a Non-Coherent Deeply Integrated Navigation Algorithm and a Tightly Coupled Navigation Algorithm ........................................ 225
Matthew Lashley, David M. Bevly

Improving the Performance of Portable Navigation Devices by Using Partial IMU Based GPS/INS Integration Technology .......................................................... 232
Xiaoji Niu, Shaowei Han

Particle Filtering Algorithm for Ultra-tight GNSS/INS Integration ........................................ 239
David Bernal, Pau Closas, Juan A. Fernandez-Rubio

Improvement of GNSS Signal Acquisition Using Low-Cost Inertial Sensors .......................... 247
Damien Kubrak, Michel Monnerat, Geraldine Artaud, Lionel Ries

Integrating External Position Information with GPS using Existing GPS Processing Software for Precision Agriculture Applications ...................................................... 258
Anthony Cole

Modified Gaussian Sum Nonlinear Filters for INS/GPS Integrated Systems .......................... 267
M. Nakagawa, H. Okuno, T. Sato, Y. Kubo, S. Sugimoto

Pseudolite Navigation for Rotorcraft and Ground-Based Vehicles ........................................ 279
Darin W. Brekke, Derek Wilson, Andrew Brown

Loran Coverage Availability Simulation Tool ........................................................................ 291
Sherman C. Lo, Benjamin B. Peterson, C.O. Lee Boyce Jr., Per K. Enge

Urban Positioning using Signals of Applicability .................................................................. 302
Greg Gerten

Active RFID for Positioning Using Trilateration and Location Fingerprinting Based on RSSI .................................................................................................................. 309
Qing Fu

Seamless Outdoor-to-Indoor Pedestrian Navigation using GPS and UWB .................................. 322
David S. Chiu, Kyle P. O’Keefe

Aerial Navigation in GPS-denied Environments using a Closed-feedback Error Loop Between the Navigation and Imaging Sensors ................................................. 334
Dorota A. Grejner-Brzezinska, Charles K. Toth, Young-Jin Lee, Jaehong Oh
<table>
<thead>
<tr>
<th>Title</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Locata Performance in the Presence of WiFi Interference: Test Results</td>
<td>341</td>
</tr>
<tr>
<td>Development and Flight Test of a Robust Optical-Inertial Navigation System Using Low-Cost Sensors</td>
<td>346</td>
</tr>
<tr>
<td>Passive Positioning System Based on Double GEO Satellite and Error Correction Models</td>
<td>358</td>
</tr>
<tr>
<td>GPS and GNSS in the Future PNT Environment</td>
<td>365</td>
</tr>
<tr>
<td>GLONASS in a Multi-GNSS World</td>
<td>371</td>
</tr>
<tr>
<td>European GNSS Programmes and the Future of GNSS</td>
<td>384</td>
</tr>
<tr>
<td>Enhancements of the Range Consensus Algorithm (RANCO)</td>
<td>394</td>
</tr>
<tr>
<td>Influence of GNSS Integrity Monitoring on Single and Multiple Fault Event Probabilities</td>
<td>405</td>
</tr>
<tr>
<td>A Sensitivity-based Method for Fault Detection and Identification</td>
<td>417</td>
</tr>
<tr>
<td>Multi-Constellation RAIM for Simultaneous Double-Fault Satellite Scenarios</td>
<td>424</td>
</tr>
<tr>
<td>Evaluation of Multi-system Integrity Algorithms</td>
<td>433</td>
</tr>
<tr>
<td>RAIM Performance in the Post SA Era</td>
<td>440</td>
</tr>
<tr>
<td>A New Method for Detection, Identification and Mitigation of Outliers in Receiver Autonomous Integrity Monitoring (RAIM)</td>
<td>452</td>
</tr>
<tr>
<td>EUROCONTROL Policy on GNSS</td>
<td>460</td>
</tr>
<tr>
<td>Availability of GNSS Performance to Support ADS-B</td>
<td>467</td>
</tr>
<tr>
<td>EGNOSATC: A Prototype for the Generation of NOTAM for European EGNOS Flight Procedures</td>
<td>475</td>
</tr>
<tr>
<td>Performance of a Doppler-Aided GPS Navigation System for Aviation</td>
<td>490</td>
</tr>
<tr>
<td>Ionospheric Delay Estimation in a Single Frequency Mode for Civil Aviation</td>
<td>499</td>
</tr>
<tr>
<td>Near Real-Time Geo-Referenced UAV Imagery Collection and Web-Based Processing on a Server for Targeting and Mapping</td>
<td>510</td>
</tr>
<tr>
<td>Estimating Angle of Attack and Sideslip Under High Dynamics on Small UAVs</td>
<td>516</td>
</tr>
</tbody>
</table>

Faisal A. Khan, Chris Rizos, Andrew G. Dempster
Michael B. Nielsen, John F. Raquet, Michael Veth, Meir Pachter
Rui Li, Yongchao Wang, Jun Zhang, Yanbo Zhu
John G. Grimes
Yury Nosenko
Paul Verhoef
Georg Schroth, Markus Rippl, Alexandru Ene, Juan Blanch, Boubeker Belabas, Todd Walter, Per Enge, Michael Meurer
Jason Rife
Yun Wu, Jinling Wang
Zhang Miaoyan, Zhang Jun, Qin Yong
P.F. Silva, M. Marcote, N. Schaeffer, J.F.M. Lorga, A. Fernandez
Tim Murphy, Matt Harris
Hiroshi Isshiki
F. Salabert, A. Hendriks, R. Rawlings, R. Farnworth
Matt Harris, Tim Murphy
Maria D. Mota, Jesus Cegarra, Daniel Zapata, Jose M. Bermudez, Emilio J. Gonzales
Tsung-Yu Chiou, Jiwon Seo, Todd Walter, Per Enge
Christophe Ouzeau, Christophe Macabiau, Benoit Roturier, Mikaël Mabileau, Laurent Azoulai, Jacqueline Levan, Frédéric Besse
Alison Brown, Bruce Bockius, Dave Wetlesen, Jim Dalrymple
John Perry, Ahmed Mohamed, Baron Johnson, Rick Lind
Fully Automatic Taxiing Takeoff and Landing of a UAV only with a Single-Antenna GPS Receiver .......................................................... 52
Am Cho, Jihoon Kim, Sanghyo Lee, Dongkeon Kim, Changdon Kee, Jane C. Doe

Performance Evaluation of Low Cost Multi-Antenna GPS/INS for Small UAVs .......................................................... 533
Rui Hirokawa, Ryusuke Ohata, Taro Suzuki, Takuiji Ebinuma

The New L2C GPS Code: Signal and Positioning Quality Analysis .......................................................... 544
Mattia De Agostino, Marco Piras, Chiara Porporato

Performance Evaluation of L2C Data/Pilot Combined Carrier Tracking .......................................................... 553
Kannan Muthuraman, Richard Klukas, Gerard Lachapelle

Evaluation of the New WAAS L5 Signal .......................................................................................... 562
Hyunho Rho, Richard B. Langley

Investigation of Upload Anomalies Affecting IIR Satellites in October 2007 .......................................................... 574
Karl Kovach, John Berg, Victor Lin

Evaluation of Compass Ambiguity Resolution Performance Using Geometric-Based Techniques with Comparison to GPS and Galileo .......................................................... 583
Wei Cao, Kyle O’Keefe, M. Elizabeth Cannon

Development of Ultimate Seamless Positioning System Based on QZSS IMES .......................................................... 593
Dinesh Manandhar, Kakuyuki Okano, Makoto Ishii, Hideyuki Torimoto, Satoshi Kogure, Hiroaki Maeda

C-Band User Terminal Tracking Loop Stability Analysis for European GNSS Evolution Programme .................. 601
Jong-Hoon Won, Bernd Eissfeller, Andreas Schmitz-Pfeiffer, Enrico Colzi

Volume 2

Multichannel Dual Frequency GLONASS Software Receiver .......................................................... 614
S. Abbasian Nik, M.G. Petovello

Design of a Regional Navigation Satellite System Constellation Using Genetic Algorithms .......................................................... 625
Halil I. Ozdemir, John F. Raquet, Gary B. Lamont

Assessment on the Use of C-Band for GNSS within the European GNSS Evolution Programme .......................................................... 637

Analysis of GPS Monitor Station Exclusions with Architecture Evolution Plan .......................................................... 647
B.J. Stanton, Ralph Strother, Walter P. Petrofski

GPS Pseudorange Measurement Calibration .......................................................................................... 657
Michael D. Menn, Xuandzung T. Tran

Evaluation of Positioning Accuracy with Differential GPS/GLONASS .......................................................... 669
Hideki Yamada, Tomoji Takasu, Nobuaki Kubo, Akio Yasuda

The Impact of Compass/Beidou-2 on Future GNSS: A Perspective from Asia .......................................................... 675
Yu-Sheng Huang, Meng-Lun Tsai

The Constellation Design of Taiwan’s Regional Navigation Satellite System .......................................................... 687
He-Chin Chen, Yu-Sheng Huang, Meng-Lun Tsai, Kai-Wei Chiang

GPS III Integrity Concept .......................................................................................... 698
Karl Kovach, John Dobyn, Mark Crews, Calvin Miles

David Fernandez Pinté, Michael Schoenhuber, Otto Koudelka
Design and Implementation of a Multi-Signal-Structure GNSS Signal Simulator
Using Low IF Digital Quadrature Modulation
Yanhong Kou, Bo Zhang, Yun Zhao

Integrating High Resolution Terrain Data into Global PDOP Calculations
Mark A. Staley, Michael A. Brilleslyper

Dilution of Precision Factor in Medium Earth Orbit Search and Rescue Systems
Richard Paiement, Mario Caron, Xiaobin Tang

Real-Time Data Disseminator (RTD2) for Simulation Systems and Integration Testing
Ben Gerten, Greg Gerten

GNSS Signal Analysis and Monitoring Tools Developed within the SWAN Project
Emanuela Falletti, Beatrice Motella, Davide Margaria, Luca Giugno, Marco Luise, Riccardo Marracci, Francesco Longo

Real-Time Environment and Sensors Simulor for Rail Applications
P. D'Angelo, S. Gomez de Aguero, D. De Castro, A. Fernandez, J. Diez, A. Albanese, L. Foglia

SEXTANT: A High-Fidelity Navigation Simulation Testbed
Kevin M. Betts, Brandon K. DeKock, Donald L. Reed, Jason Gewehr, Derrick Bezanson

Signal Compression for an Efficient and Simplified GNSS Signal Parallel Acquisition
Maurizio Fantino, Marco Pini, Paolo Mulassano, Gianmarco Girau, Mario Nicola, Alessandro Nordio

Direct P(Y)/M-code Acquisition Based on Time-Frequency Folding Technique
Hong Li, Mingquan Lu, Zhenming Feng

Reduced Complexity Circuits for Serial Code Phase Search Acquisition
Gianmarco Girau, Letizia Lo Presti, Maurizio Fantino

Bayesian Direct Position Estimation
Pau Closas, Carles Fernandez-Prades, David Bernal, Juan A. Fernandez-Rubio

Noise Floor Independent Delay Lock Loop Discriminator
Gang Xie, Xiang Yuan

GNSS Receiver with Vector Based FLL-Assisted PLL Carrier Tracking Loop
Stefan Kiesel, Christian Ascher, Daniel Gramm, Gert F. Trommer

Hotstart Every Time – Compute the Ephemeris on the Mobile
Philip G. Mattos

A Dynamic Satellite Search Scheduling for GNSS Super Constellation
Kun-Tso Chen

Pull-out Probability and Tracking Threshold Analysis for High Dynamics GNSS Carrier Loops
Pedro A. Roncaglio, Javier G. Garcia, Carlos H. Muravchik

Block Correlator for Tracking GPS/GNSS Signals
Phani K. Sagiraju, Pradeep Kashyap, David Akopian

Filtering IF Samples to Reduce the Computational Load of Frequency Domain Acquisition in GNSS Receivers
Sana Ullah Qaisar, Nagaraj C. Shivaramaiah, Andrew G. Dempster, Chris Rizos

Differences in Multipath Propagation Between Urban and Suburban Environments
Alexander Steingass, Andreas Lehner

Impact of Near-Field Effects on the GNSS Position Solution
Florian Dilssner, Guenter Seeber, Gerhard Wuebbena, Martin Schmitz
A New Wavelet-Based Multipath Mitigation Technique
Mohamed Elhabiby, Ahmed El-Ghazouly, Naser El-Sheimy

Performance of GNSS Time of Arrival Estimation Techniques in Multipath Environments
Ali Broumandan, Tao Lin

Particle Filtering Strategies for Efficient Multipath Mitigation
Pau Closas, Carles Fernandez-Prades, Juan A. Fernandez-Rubio, David Bernal

BOC/MBOC Multicorrelator Receiver with Least-Squares Multipath Mitigation Technique
Fernando D. Nunes, Fernando M.G. Sousa, Jose M.N. Leitao

Demonstration of a Synthetic Phased Array Antenna for Carrier/Code Multipath Mitigation
T. Pany, B. Eissfeller

Analysis of Early Late Phase for Multipath Mitigation
Omer Mohsin Mubarak

A Geometrical Approach for Maximum Likelihood Estimation of Multipath
Nuria Blanco-Delgado, Fernando D. Nunes, Joao M. Xavier

GPS Multipath Parameterization using the Extended Kalman Filter and a Dual LHCP/RHCP Antenna
Ashkan Izadpanah, Cillian O'Driscoll, Gerard Lachapelle

Smart Positioning with Fastrax's Software GPS Receiver Solution
S. Soderholm, T. Jokitalo, K. Kaisti, H. Kuusniemi, H. Naukkarinen

A Single Die GPS, with Indoor Sensitivity - the NXP GNS7560
T. Haddrell, J.P. Bickerstaff, M. Conta

Achieving 30 cm Autonomous Positioning Accuracy with Nexteq Single-Frequency GPS Receivers
Y. Zhang, S. Lee, C. Chen

Galileo Receiver Testing with the GNSS Signal Generator NSG 5100
S. Martin, S. Diefenbach, D. Felbach, M.v. Voithenberg, H. Dietz, R. Sasum

A Versatile Solution for Testing GPS/Inertial Navigation Systems
Neal Fedora, Colin Ford, Peter Boulton

Performance Evaluation of the Multi-Constellation and Multi-Frequency GNSS RF Navigation Constellation Simulator NavX - NCS
Guenter Heinrichs, Markus Irsigler, Robert Wolf, Guenther Prokoph

magicGNSS: Precise GNSS Products Out of the Box
R. Piriz, A. Mozo, P. Navarro, D. Rodriguez

Galileo Performance Analysis Software for Test User Receivers
Sonsoles Romero, Jose Diez, Antonio Fernandez, Axel Van den Berg, Maria Simsly, Kristoff Van Wassenhove, Richard Morgan-Owen, Juan Carlos de Mateo, Martin Hollreiser

GPStream: A Low Bandwidth Architecture to Deliver or Autonomously Generate Predicted Ephemeris
Eric Derbez, Rich Lee

Continuous GNSS Performance Monitoring, Prediction and Information Services via GalTeC
W. Ehret H. Su, E. Kubitz, O. Glaser, E. Bromenhofer

Comparison of Assisted and Stand-Alone Methods for Increasing Coherent Integration Time for Weak GPS Signal Tracking
Pejman L. Kazemi, Cillian O'Driscoll

Differential Joint Data/Pilot Acquisition Strategies for Indoor Galileo E1 Signal
Tung Hai Ta, Letizia Lo Presti, Fabio Dovis, Davide Margaria, Riccardo Lesca
<table>
<thead>
<tr>
<th>Title</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>A New Statistical Model of the Indoor Propagation Channel for Satellite Navigation</td>
<td>1061</td>
</tr>
<tr>
<td>Matteo Paonni, Victoria Kropp, Andreas Teuber, Guenter W. Hein</td>
<td></td>
</tr>
<tr>
<td>Combined L1 / L2C Tracking Scheme for Weak Signal Environments</td>
<td>1071</td>
</tr>
<tr>
<td>Cyril Gernot, Kyle O’Keefe, Gerard Lachapelle</td>
<td></td>
</tr>
<tr>
<td>Ubiquitous Wifi/GNSS Positioning System - TOA Based Distance Estimation</td>
<td>1086</td>
</tr>
<tr>
<td>Kazimieras Bagdonas, Kai Borre</td>
<td></td>
</tr>
<tr>
<td>DINGPOS: A Hybrid Indoor Navigation Platform for GPS and GALILEO</td>
<td>1093</td>
</tr>
<tr>
<td>Effects of Oversampling and Multipath on Navigation Using OFDM Signals of Opportunity</td>
<td>1105</td>
</tr>
<tr>
<td>Christopher M. Schexnayder, John F. Raquet, Richard K. Martin</td>
<td></td>
</tr>
<tr>
<td>Augmentation of Low-cost GPS/MEMS INS with UWB Positioning System for Seamless Outdoor/Indoor Positioning</td>
<td>1117</td>
</tr>
<tr>
<td>Makoto Tanigawa, Jeroen D. Hol, Fred Dijkstra, Henk Luinge, Per Slycke</td>
<td></td>
</tr>
<tr>
<td>Active RFID Fingerprinting for Indoor Positioning</td>
<td>1125</td>
</tr>
<tr>
<td>Guenther Retscher, Qing Fu</td>
<td></td>
</tr>
<tr>
<td>GPS Position Aiding in a Cellular Telephone without the Network</td>
<td>1134</td>
</tr>
<tr>
<td>M.R. Jarvis, R.W. Rome, P.J. Duffett-Smith, A.R. Pratt</td>
<td></td>
</tr>
<tr>
<td>Implementation and Analysis of an SDR Processor for GNSS Software Correlators</td>
<td>1142</td>
</tr>
<tr>
<td>Gotz Kappen, Volker Pieper, Lothar Kurz, Tobias G. Noll</td>
<td></td>
</tr>
<tr>
<td>A Real-Time Software Receiver for the GLONASS L1 Signal</td>
<td>1152</td>
</tr>
<tr>
<td>Senlin Peng, Brent M. Ledvina</td>
<td></td>
</tr>
<tr>
<td>System Aspects and Practical Results for Precise Car Navigation with Modern Civil Signals using a Software Receiver</td>
<td>1164</td>
</tr>
<tr>
<td>Daniel Sanroma Guixens, Dominik Dotterbock, Thomas Pany, Bernd Eissfeller</td>
<td></td>
</tr>
<tr>
<td>Design and Analysis of Reconfigurable Embedded GNSS Receivers using Model-Based Design Tools</td>
<td>1177</td>
</tr>
<tr>
<td>Shankararaman Ramakrishnan</td>
<td></td>
</tr>
<tr>
<td>Optimum Digital Filters for GNSS Tracking Loops</td>
<td>1188</td>
</tr>
<tr>
<td>Pejman L. Kazemi</td>
<td></td>
</tr>
<tr>
<td>Assessing the Spoofing Threat: Development of a Portable GPS Civilian Spoofers</td>
<td>1198</td>
</tr>
<tr>
<td>Todd E. Humphreys, Brent M. Ledvina, Mark L. Psiaki, Brady W. O'Hanlon, Paul M. Kintner Jr.</td>
<td></td>
</tr>
<tr>
<td>FPGA-Optimized GNSS Receiver Implementation Techniques</td>
<td>1210</td>
</tr>
<tr>
<td>H. Stewart Cobb</td>
<td></td>
</tr>
<tr>
<td>Real-Time Multipath Monitoring and Characterization with a Variable Spacing Correlator on a FPGA-Based Software GNSS Receiver</td>
<td>1216</td>
</tr>
<tr>
<td>Jean-Christophe Guay, Bruno Sauriol, Marc-Antoine Fortin</td>
<td></td>
</tr>
</tbody>
</table>

**Volume 3**

<table>
<thead>
<tr>
<th>Title</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>Snapshot Positioning for Unaided GPS Software Receivers</td>
<td>1227</td>
</tr>
<tr>
<td>Yi Qian, Xiaowei Cui, Mingquan Lu, Zhenming Feng</td>
<td></td>
</tr>
<tr>
<td>Comparison of GPS Tracking Loop Performance in High Dynamic Condition with Nonlinear Filtering Techniques</td>
<td>1235</td>
</tr>
<tr>
<td>Sung-Hyuck Im, Jong-Hwa Song, Gyu-In Jee, Chan-Gook Park</td>
<td></td>
</tr>
</tbody>
</table>
A Dual-Stacked Reflector Antenna that Produces Equal Strength Circular Polarized L-Band Signals Everywhere on Earth for GPS Satellite Applications
Yong U. Kim, Frank M. Czopek

A New Approach to Cellphone GPS Antennas
T. Haddrell, M. Phocas, N. Ricquier

An Analysis of Multipath Mitigation Techniques Suitable for Geodetic Antennas
Robin Granger, Steve Simpson

Simulations of Antennas Mounted on Rotorcrafts
Inder J. Gupta, Khadir A. Griffith

Adaptive Array Phase Control using an Integrated Software GPS Signal Processing Architecture
Sai K. Kalyanaraman, Michael S. Braasch

Mitigation of Continuous and Pulsed Radio Interference with GNSS Antenna Arrays
Andriy Konovaltsev, David S. De Lorenzo, Achim Hornbostel, Per Enge

Optimum Adaptive Filtering for GNSS Antenna Arrays
Andrew J. O'Brien, Inder J. Gupta

Post-Processing Dynamic GNSS Antenna Array Calibration and Deterministic Beamforming
Staffan Backen, Dennis M. Akos, Magnus L. Nordenvaad

Interference Mitigation Technique using DOA Information of Interferences for the GPS Receiver
Geon Woo Lee, Deok Won Lim, Chansik Park, Dong-Hwan Hwang, Sang Jeong Lee

The Study of Typhoon Path in Taiwan Region Using Precise Point Positioning Technique
Wei-Chih Peng, Yu-Hwa Lee, Kai-Wei Chiang, Ming Yang

Troposphere Modeling for Precise GPS Rapid Static Positioning in Mountainous Areas
P. Wielgosz, S. Cellmer, Z. Rzepecka, D.A. Grejner-Brzezinska

Estimation of Troposphere Decorrelation Using the Combined Zenith-dependent Parameter
Yong Won Ahn, Don Kim, Peter Dare, James Park

Assessing Space-based GNSS Technology for Meteorological Studies in Australia
Erjiang Fu

Real-Time Detection of Ionospheric Scintillations and Potential Applications
Irma Rodriguez, Carlos Hernandez, Ana Curiel, Carlos Catalan, Laura Fernandez, Esther Sardon

Diffraction Tomography of the Disturbed Ionosphere Based on GPS Scintillation Data
Mark L. Psiaki, Gary S. Bust, Alessandro P. Cerruti, Paul M. Kintner Jr., Steve P. Powell

Evaluating GPS Receiver Robustness to Ionospheric Scintillation
Joanna C. Hinks, Todd E. Humphreys, Brady O’Hanlon, Mark L. Psiaki, Paul M. Kintner Jr.

The MIM-Principle Where GNSS and Radio Astronomy Collide
E. Noordam

A Demonstration of L2C Tracking from Space for Atmospheric Occultation
T.K. Meehan, Chi O. Ao, Byron Iijima, David Robison, Doug Hunt, Christian Rocken, Bill Schreiner, Sergey Sokolovskiy

MMS-IRAS TRL-6 Testing
Gregory W. Heckler, Luke B. Winternitz, William A. Bamford

Next Space-VLBI Mission, VSOP-2, and the Precise Orbit Determination with GNSS Navigation and SLR
Yoshiharu Asaki, Hiroshi Takeuchi, Makoto Yoshikawa
Short-term Stability of GNSS Satellite Clocks and its Effects on Precise Point Positioning

Anja Hesselbarth, Lambert Wanninger

GPS Precise Absolute Positioning via Kalman Filtering

Brian Tolman

Models and Algorithms Evaluation on GPS Kinematic Precise Point Positioning

Congwei Hu, Wu Chen, Jicang Wu

A Time-Relative Approach for Precise Positioning with a Miniaturized L1 GPS Logger

J. Traugott, G. Dell’Omo, A.L. Vyssotski, D. Odijk, G. Sachs

ATOM: Super Compact and Flexible Format to Store and Transmit GNSS Data

Igor Artushkin, Aleksey Boriskin, Dmitry Kozlov

Assessment of the Higher Order Ionosphere Error on Position Solutions

Y.T. Morton, Frank van Graas, Qihou Zhou, Jeffrey Herdtner

Mitigation of the Ionospheric Range Error in Single-frequency GNSS Applications

C. Mayer, N. Jakowski, J. Beckheimrich, E. Engler

Local Models in Ionosphere VTEC Estimation Based on GNSS Regression Models

Seigo Fujita, Hiroaki Yamamoto, Yukihiro Kubo, Sueo Sugimoto

Retrieving Vertical Ionospheric Electron Density Profile with an Improved Abel Inversion Algorithm

Gary Ouyang, Jinling Wang

Evaluation of Deep Signal Fading Effects Due to Ionospheric Scintillation on GPS Aviation Receivers

Jiwon Seo, Todd Walter, Tsung-Yu Chiou, Juan Blanch, Per Enge

Inter-frequency Bias Estimation for the GPS Monitor Station Network

Donny Holaschutz, Robert H. Bishop, R. Benjamin Harris, Brian Tolman

A New Technique to Improve the Electron Density Retrieval Accuracy: Application to FORMOSAT-3/COSMIC Constellation

Angela Aragon-Angel

Investigation of Scintillation Characteristics for High Latitude Phenomena

S. Skone, F. Man, F. Ghafoori, R. Tiwari

Regional TEC Model using Improved Neural Network and its Application in Single Frequency Precise Point Positioning

Chengquan Xu, Zhao Li, Xianghong Hua, Qian Fan

Generation of Third Code and Phase Signals Based on Dual-Frequency GPS Measurements

Bofeng Li

Three Carrier Ambiguity Resolution: Generalised Problems, Models, Methods and Performance Analysis using Semi-Generated Triple Frequency GPS Data

Yanming Feng, Bofeng Li

Performance Evaluation of GPS/Galileo Multiple-frequency RTK Positioning Using a Single-difference Processor

Wei Cao, Kyle O’Keefe, M. Elizabeth Cannon

Towards Single Epoch Ambiguity Resolution with Galileo Multiple Frequency Using Improved Cascading Ambiguity Resolution (CAR) Method

Wu Chen, Shengyue Ji, Xiaoli Ding, Yongqi Chen, Congwei Hu

GPS-GLONASS RTK: Making the Choice Between Civilian and Military L2 GLONASS

Frank Boon, Jean-Marie Sleewaegen, Andrew Simsky, Wim De Wilde

Improving Performances of Classic Three Carrier Ambiguity Resolution (TCAR) Algorithms for Galileo using GTCAR

Javier Simon, Belen Martin Peiro, Manuel Toledo

Geoassets
Estimation of GPS-GLONASS System Time Difference with Application to PPP ............................ 1818
Changsheng Cai, Yang Gao

Development and Field-Testing of a GPS-Based Mountain Pass Road Opening
Driver Assistance System .................................................................................................................. 1826
Kin S. Yen, Michael T. Darter; Ty A. Lasky, Bahram Ravani

Volume 4

Navigation and Sensor Integration in an Autonomous Lawnmower ........................................ 1837
Adam Webb, Brian Birkmire, Jeffrey Baugher, Kuldip S. Rattan, Scott Thomas, John Gallagher

Mini Urban Challenge .................................................................................................................. 1843
Casey C. Miller, Caroline A. New

Adaptive Sensing for Improving Detection of Unexploded Ordnances with a Sigma-Point Information Filter ........................................................................................................ 1850
Alan Y. Chen

Mitigating Geomagnetic Noise in Airborne Magnetic Surveys using GPS ................................ 1861
Susan Skone

A New GPS-Enhanced High Resolution Weather Service ............................................................ 1867
Tetsuya Iwabuchi, Christian Rocken

An Energy Scavenging Autonomous Surface Vehicle for Littoral Surveillance ........................ 1876
Gabriel Hugh Elkaim, C.O. Lee Boyce

Cooperative LBS for Secure Transport System .......................................................................... 1885
Andrea Tomatis, Pasquale Cataldi, Giovanni Pau, Paolo Mulassano, Fabio Dovis

Micro-Navigation Satellite Network Design and Analysis .......................................................... 1891
Bei Kang, Jong-Ha Lee, Chang-Hee Won

Improving User Experience in Assisted Land Navigation Using Sub-optimal Sensor Configuration Installed on a Cell Phone ............................................................... 1901
Goutam Dutta, Hemanth Mullur, June Chul Roh, Sandeep Rao, Srinath Hosur

Twin IMU-HSGPS Integration for Pedestrian Navigation ......................................................... 1907
Jared B. Bancroft, Gérard Lachapelle, M. Elizabeth Cannon, Mark G. Petovello

GNSS Aided In Situ Human Lower Limb Kinematics During Running ..................................... 1918
S.P. Kwakkel, G. Lachapelle, M.E. Cannon

A Solution for Combined GPS/GLONASS Navigation in Conditions of Limited Satellite Visibility ....................................................................................................................... 1928
Changsheng Cai

Instantaneous RTK Positioning Based on User Velocity Measurements .................................... 1936
Nobuaki Kubo, Sam Pullen

A Hybrid System for Navigation in GPS-Challenged Environments: Case Study ..................... 1948
Chris Rizos, Dorota A. Grejner-Brzezinska, Charles K. Toth, Andrew G. Dempster, Yong Li, Noni Politi, Joel Barnes, Hongxing Sun

Precise Point Positioning with Single-Frequency Mass Market Receivers ................................ 1959
A. Somieski, E. Favey, C. Burgi

The Usefulness of Internet-based (NTrip) RTK for Navigation and Intelligent Transportation Systems .................................................................................................................. 1967
Marcin Uradzinski, Don Kim, Richard Langley

A Zonal Regional Augmentation System Applying on Railway and Inland Waterway ............. 1976
Wang Zhipeng, Zhang Jun, Liu Qiang
Performance of Hourly Precise Point Positioning with Ambiguity Resolution
Jianghui Geng, Xiaolin Meng, Norman Teferle, Alan Dodson, Maorong Ge, Chuang Shi, Jingnan Liu

Quality Assessment of DTM Generated from RTK GPS Data on Area with Various Sky Views
Abdul Nasir Matori, Dedi Atunggal, B.K. Cahyono

WASS Benefits of GEO Ranging
Timothy Schempp, Jason Burke, Arthur Rubin

A Simple Algorithm for Dual Frequency Ground Monitoring Compatible with ARAIM
Juan Blanch, Todd Walter, Per Enge

Modeling Ionospheric Spatial Threat Based on Dense Observation Datasets for MSAS
Takeyasu Sakai, Keisuke Matsunaga, Kazuaki Hoshinoo, Todd Walter

A New Modeling Scheme of Satellite Ephemeris and Clock Errors for Korean WADGPS Test Bed
Doyoon Kim, Ho Yun, KyoungHo Sohn, Changdon Kee

Reconstructing the WAAS Undersampled Ionospheric Gradient Threat Model for the WAAS Expansion into Mexico
Ephrem Paredes, Nitin Pandya, Lawrence Sparks, Attila Komjathy

Architecture of an FAA Certified TSO-C145c Precision Approach Receiver
R.A. Nayak, J.K. Ray

Enhanced SBAS Integration Method Using Combination of Multiple SBAS Corrections
Ho Yun, Doyoon Kim, Sanghoon Jeon, Byungwoon Park, Changdon Kee

Performance Assessment of a Local Area Monitoring System in Asia Pacific Region
Chun-Hao Chen, Shau-Shiun Jan

Off-line, On-line and On-target FD/FDE Test Results for Approach Phases in an Aviation Receiver
J.K. Ray, R.A. Nayak

NASA RNSS Spectrum Protection Activities
Beryl Brodsky, James E. Hollansworth, James J. Miller, A.J. Oria

The L5 Demo Payload on GPS Mission IIR-20
Thomas D. Powell, Clyde E. Edgar, Hakan Ozisik, Mike McFadden, Dan Reigh, Rich Spieth, James Irvine, Gary Vautin

GNSS Receiver Testing Focusing on Strong Interference by Use of a Hardware Signal Simulator
Holmer Denks, Achim Hombostel, Jean-Michel Pierre

Precise Positioning of Ships and Buoys in the Open Ocean - Results from a 3-Month Indian Ocean Cruise, and a Tsunami Buoy off Japan's Coast
C. Rocken, T. Iwabuchi, Z. Lukes, L. Mervart, M. Fujita, M. Kanzaki

A Study on the Dissemination of Network-Based DGPS Corrections for e-Navigation
Ki-Yeol Seo, Sang-Hyun Park, Jin-Kyu Choi, Sang-Hyun Suh

A Feasibility Study on L1/L2C Software RSIM for Marine DGPS
Sang-Hyun Park, Deuk Jae Cho, Ki Yeol Seo, Sang-Hyun Suh

Integrating Monolithic Ring Laser Gyros with Legacy Shipboard Navigation and Weapons Systems to Improve Inertial Navigation System Performance

Validation of the Offset Precision Approach with Vertical Guidance to Landing Using LAAS as Sole Means of Navigation
Yih-Ru Peter Huang, John Fagan, Yu-Zhen Xue, Gerry McCartor

Solutions to Issues of GBAS using SBAS Ranging Source Signals
Susumu Saito, Naoki Fujii, Kazushi Suzuki, Takeshi Ono
High Performance Navigation Algorithms for Aviation - Results of Approach and Airport Surface Movement Tests .......................... 2142
Wolfgang Schuster, Jie Bai, Washington Ochieng, Per Martin Schachtebeck, Meiko Steen

Trimble’s Marine Reference Station Modernization .................................................. 2150
Kendall E. Ferguson, Michael K. Albright, Markus Brandl

Continuity and Integrity Aspects of an Integrated GBAS-INS Navigation System ...... 2161
Meiko Steen, Thomas Feuerle, Ulf Bestmann, Mirko Stanisak, Peter Hecker

Cascade Dual Frequency Smoothing Performance Evaluation Study .................... 2170
Rui Xue, Jun Zhang, Yanbo Zhu

Ionospheric Spatial Gradient Monitoring by using a Long Baseline Monitor with Integrity Algorithms ................................................................. 2179
Jeongrae Kim, Myeon-Sook Jeong, Jongsun Ahn, Young Jae Lee

Performance Assessment of GBAS CAT III using GPS and Galileo ....................... 2186
B. Belabbas, P. Remi, M. Meurer

PORIMA - Precise Predicted Orbit Based Receiver Integrity Monitoring Algorithms .... 2194
Hua Su, Walter Ehret

Receiver Carrier-to-Noise Ratio Monitoring Based on Improved Cumulative Sum (CUSUM) Method .............................................................. 2203
Liu Xia, Zhang Xuejun, Xue Rui

Real-Time, Wide-Area, Precise Kinematic Positioning Using Data from Internet NTRIP Streams .......................................................... 2210
Oscar L. Colombo

Incorporation of Network Information in Multiple GNSS Processing Environment .... 2221
Hans-Juergen Euler, Joachim Wirth

The Relationship Between Network RTK Solutions MAC, VRS™, PRS, FKP and i-MAX ..... 2231
Frank Takac, Oliver Zelzer

User Terminal/Local Element System for Network Based Positioning using RTK/EGNOS in Urban Environment .................................................. 2239
Antonio Defina, Khalid Charqane, Fabrizio Dominici, Gianluca Marucco, Chiara Porporato, Mattia De Agostino, Ambrogio M. Manzino

Transferring Ambiguity Levels Between Network Corrections ............................... 2251
P. Alves, P.M. Grgich

Algorithms to Calibrate and Compensate for GLONASS Biases in GNSS RTK Receivers working with 3rd party Networks ........................................ 2259
Aleksey Boriskin, Gleb Zyryanov

Toward the Ultimate RTK: The Last Challenges in Long-Range Real-Time Kinematic Applications ................................................................. 2268
Don Kim, Richard B. Langley

Precise Point Positioning with Ambiguity Resolution in Real-Time ......................... 2280
Leos Mervart, Zdenek Lukes, Christian Rocken, Tetsuya Iwabuchi

Investigating the Impact of the Commercial GSM/GPRS Communications on the Availability of the Network Based RTK GNSS Service ...................... 2289
Jose Aponte, Xiaolin Meng, Terry Moore, Chris Hill, Mark Burbidge

A Triple Estimating Receiver of Multiplexed Binary Offset Carrier (MBOC) Modulated Signals ................................................................. 2295
M.S. Hodgart, R.M. Weiler, M. Unwin

Revised PRN Code Structures for Galileo E1 OS .................................................. 2305
Stefan Wallner, Jose-Angel Avila-Rodriguez, Jong-Hoon Won, Günter Hein, Jean-Luc Issler

An Interference Impact Assessment Model for GNSS Signals ................................. 2318
Beatrice Motella, Simone Savasta, Davide Margaria, Fabio Dovis
GNSS Offline Signal Quality Assessment ................................................................. 2327
M. Soellner, C. Kurzhals, G. Hechenblaikner, M. Rapisarda, T. Burger, S. Erker, J. Furthner,
U. Grunert, M. Meurer, S. Tholert

Mitigating the Impact of GNSS Signals in the Radio Astronomy Band 1610.6-1613.8 MHz .. 2339
Olivier Julien, Jean-Luc Issler

Interference Effects on Galileo E5b and E6 Frequencies Observed in the Galileo Test and Development Environment GATE .................................................................................................................. 2351
Guenter Heinrichs, Erwin Loehnert, Bjoern Ott, Elmar Wittmann

C-Band user Terminal Concepts and Acquisition Performance Analysis for European GNSS Evolution Programme .................................................................................................................. 2358
Jong-Hoon Won, Bernd Eissfeller, Berthold Lankl, Andreas Schmitz-Peiffer, Enrico Colzi

Galileo Signal Fading in an Indoor Environment .......................................................... 2370
Andreas Teuber, Matteo Paonni, Victoria Kropp, Guenter W. Hein

AltBOC for Dummies or Everything You Always Wanted to Know About AltBOC ........... 2379
Laurent Lestarquit, Geraldine Artaud, Jean-Luc Issler

GPS - GALILEO Urban Interoperability Performance with the GPS - GALILEO Time Offset ................................................................................................................................. 2389
Bernard Bonhoure, Inge Vanschoenbeek, Marco Boschetti, Jerome Legenne

Consequences of MBOC Approximation by BOC Modulation ........................................ 2400
F. Macchi M.G. Petovello, G. Lachapelle

GALANT — Architecture Design and First Results of a Novel Galileo Navigation Receiver Demonstrator with Array Antennas .......................................................................................... 2412
Manuel Cuntz, Holmer Denks, Andriy Konovaltsev, Achim Hornbostel, Achim Dreher,
Michael Meurer

Performance of an L1/E5 GNSS Receiver using a Direct Conversion Front-end Architecture ................................................................................................................................. 2420
Ruediger M. Weiler, Paul Blunt, Philip Jales, Martin Unwin, Stephen Hodgart

A New Unambiguous Tracking Technique for Sine-BOC(2n,n) Signals ....................... 2432
Zheng Yao

Exploiting the Secondary Codes to Improve Signal Acquisition Performance in Galileo Receivers ................................................................................................................................. 2439
Nagaraj C. Shivaramaiah, Andrew G. Dempster, Chris Rizos

Volume 5

A Novel Low-Complexity Acquisition Method for Next Generation GNSS Signals .......... 2448
Pei-Hsueh Lee, Dong-Hong Liu, Wei-Lung Mao, Hen-Wai Tsao, Fan-Ren Chang, Hsin-Chung Yeh, Kun-Tso Chen

The IRGAL Project: Innovation and Research on Galileo in Piedmont ........................... 2456
Marco Pini, Maurizio Fantino, Paolo Mulassano, Letizia Lo Presti, Luigi Bragagnini

Matched Filter MBOC Tracking by Accumulation ......................................................... 2462
Jose Diez, Joao S. Silva, Antonio Fernandez

Multipath and Tracking Performance of Galileo Ranging Signals Transmitted by GIOVE-B ................................................................................................................................. 2467
Andrew Simsky, David Mertens, Jean-Marie Sleewaegen, Wim De Wilde, Martin Hollreiser,
Massimo Crisci

Galileo System Performance for Different Users and Constellations ............................. 2479
Veit Oehler, Jan M. Krueger, Hans L. Trautenberg, Julian Daubrawa

Galileo Ground Mission Segment Architecture and Performances .............................. 2491
Bernhard kleine Schlarmann, Martin Hollreiser, Francisco Amarillo