
Saint Petersburg, Russia
29 – 31 May 2017
# TABLE OF CONTENTS

**SESSION I – INTEGRATED SYSTEMS**

1. Data Processing Algorithms for MEMS Based Multi-Component Inertial Measurement Unit for Indoor Navigation.....1  
   A.G. Mikov, A.S. Galov

2. Collision Avoidance System with Situational Awareness Capabilities for Autonomous MAV Indoor Flights.....8  
   S. Prophet, G. Scholz, G.F. Trommer

3. New Method of Optical Flow Evaluation.....16  
   P.K. Kuznetsov, B. V. Martemyanov

4. Using Vision Systems to Determine the Vehicle Position on the Road.....20  
   N.I. Kotov, S.B. Berkovich, R.N. Sadekov, A.V. Sholokhov, A.S. Lychagov, U.V. Likholay

5. Application of the Convolutional Neural Network to Design an Algorithm for Recognition of Tower Lighthouses.....23  
   I.A. Shamov, P.S. Shelest

6. Transferring Navigation Information between Quadrotors in a Formation over Erasure Communication Channel with Binary Adaptive Coding.....25  
   S.I. Tomashevich, A.O. Belyavskiy

7. Robust Navigation of MAVs Based on Deeply Integrated Laser-Camera Information.....28  
   J. Atman, G.F. Trommer

8. Efficiency Analysis of Algorithms to Correct Micro-Mechanical Positioning System for the Angular Position of a Pilot’s Head.....32  
   R.V. Alaluev, V.V. Matveev, V.Ya. Raspopov, A.P. Shvedov

9. An Algorithm for Coordinate Location by Matching a Scene Photo with the Locality Map.....35  
   E.V. Gavrilov, D.D. Nikeev, V.M. Timofeev, E.A. Filippova

10. Controlling Steerable Platforms to Point Scientific Instruments at Survey Targets in the URAGAN Experiment Onboard the International Space Station.....38  

11. On Calibration of a Navigation System Equipped with a Magnetic Gradiometer.....41  
    B.V. Pavlov, E.V. Karshakov, M.Yu. Tkhtorenko

12. Control of Progress Transport Cargo Vehicles During the Experiments.....44  
    T.V. Matveeva, M.Yu. Belyaev
13. Observation Error Estimation in Case of AUV Using a Single Beacon Acoustic Positioning System.....48
   I.N. Burdinskiy, S.A. Otcheskiy

   R.V. Senchenko, N.V. Krapukhina

15. Approach to Safe Vehicle Navigation Considering Dynamics of Transport Participants in Real Time.....55
   N.V. Kamenov, N.V. Krapukhina

16. Trajectory Tracking while Measuring Distance and Bearing with the Use of Fractal Wiener Process for the Motion Model.....58
   O.S. Amosov, S.G. Baena

17. Electric Propulsion Spacecraft Guidance for Maintenance of the Lunar Base Infrastructure.....62
   O.L. Starinova, M.K. Fain

18. Automatic Landing of an Unmanned Aerial Vehicle by Means of a Ground-Based Laser Beacon System.....68
   A.V. Abakumov, I.K. Kuz'menko, D.Yu. Livshits, P.K. Nesterov, A.A. Seranova, I.V. Sergushov, V.N. Slonov

   E.A. Mikrin, M.V. Mikhailov, S.N. Rozhkov, A.S. Semyonov

20. SINS Aided GPS Integrity Monitoring for SINS/GPS Tightly Integrated Navigation System.....81
    F. Wu, C. Gu, Y.H. Zhang, R.X. Mu

21. Invariant Filter Versus Other Robust Filtering Methods Applied to Integrated Navigation.....86
    E. Robert, T. Perrot

22. Solution to One Class of Navigation Information Processing Problems by Using Adaptive Bayesian Filters.....93
    Q. Liang, Yu.A. Litvinenko, O.A. Stepanov, G.F. Trommer

23. Construction of an Optimal Flight Trajectory in the GLONASS Accuracy Field.....98
    O.N. Skrypnik, N.G. Arefyeva

24. Design of the Navigation Method of the Mechanical Gyro Based Inertial Platform System.....101
    T. Wang, Y. Zhou, W. Wang
25. A Correction Method for DVL Measurement Error by Pitch Dynamics.....105

    Around Fiber-Optic and Micromechanical Sensors.....109
   A.V. Chernodaroy, A.P. Patrikeev, A.B. Borzov, I.I. Merkulova, Ju.N.
   Korkishko, V.A. Fedorov,
   I.V. Fedorov

27. Attitude Error Compensation Technology for Inertial Platform of Airborne Gravimeter
    Based on RTS Smoothing Algorithm.....113
   X.T. Wu, Y. Yang, W. Gao, Z.S. Zhang, Z. Pei

28. Road Sign Detection and Recognition in Panoramic Images to Generate Navigational
    Maps.....117
   R.N. Sadekov, K.A. Asatryan, V.E. Prun, V.V. Postnikov, F.G. Kirdyashov, M.R.
   Koren

29. Performance-Based Navigation (PBN) with Continuous Descent Operations (CDO) for
    Efficient Approach over Highly Protected Zones.....122
   Errico, V. Di Vito

30. Development of the AUV Automatic Docking Methods Based on Echosounder and
    Video Data.....130
   A.V. Inzartsev, A.M. Pavin, N.I. Rylov

31. Vision Navigation and 3D Reconstruction of Underwater Objects with Autonomous
    Underwater Vehicle.....136
   V.A. Bobkov, A.P. Kudryashov, S.A. Melman, A.F. Scherbatyuk

32. Efficiency Evaluation for Different Kind of Localization Methods for Android Devices.....141

33. A Method of Evaluating the Accuracy of Phase Center Motion Parameters Estimation.....146
    V.I. Kulakova

34. Design Aspects of Flight and Navigation Systems for Small UAVs of Different Types.....152
    A.V. Abakumov, D.E. Gutsevich, R.V. Ernakov, D.Yu. Livshits, S.N. Romadin,
    A.A. Seranova, I.V. Sergushov, E.N. Skripal

35. Experimental Research of Distance Estimation Accuracy Using Underwater Acoustic
    Modems to Provide Navigation of Underwater Objects.....161

36. Using Satellite Receivers with a Common Clock in a Small-Sized GNSS Compass.....165
    G.I. Yemelyantsev, A.P. Stepanov, B.A. Blazhnov, D.A. Radchenko,
    I.Yu. Vinokurov, P.Yu. Petrov

37. Fault-Tolerant Airport Vehicle Integrated Navigation System.....167
    D.A. Antonov, K.K. Veremeenko, M.V. Zharkov, I.M. Kuznetsov, A.N. Pron’kin
38. Account for Constraints in Estimating Precise Pont Positioning Error under Stochastic Uncertainty.....171
   O.V. Zaitsev

39. GPS/GLONASS/BDS Multi-System Fusion Positioning Based on Optimized Nonlinear Filter.....174
   K. Duan, X. Mao

40. Using Inertial Navigation Systems to Monitor the Motion of a Train.....178

SESSION II – INERTIAL SYSTEMS AND SENSORS

41. Inertial Attitude Determination System Designed for Low-Dynamics Applications in Low-Gravity Environment.....183
   A.Szumski, B. Eissfeller

42. Dynamic Error Compensation and Parameter Optimization for RLG SINS in Vibration Environments.....191
   L. Wang, W. Wu, X. Pan

43. Analysis of SINS Structures with Error Autocompensation.....199
   D.A. Burov


45. Strapdown Inertial Navigation System of a Rotating Carrier.....213
   V.V. Matveev

46. Comparative Analysis of Application of Various Filters in Problem of Filtering Measurement Disturbances of Sensors in SINS.....215

47. A New Version of Separating the Process of Integrating the Equations of Autonomous Strapdown INS into Rapid and Slow Loops.....220
   Ya.G. Sapunkov, Yu.N. Chelnokov, A.V. Molodenkov, S.E. Perelyaev

48. Sea Development of a Strapdown Inertial Navigation System Based on Laser Gyros.....224

49. Algorithmic Compensation of Thermal Errors of Sensors of a Strapdown Inertial Unit.....228
   N.A. Elansky, D.G. Pikunov, A.I. Logachev, D.A. Turkin, F.V. Tatarinov
   N.I. Krobka

51. On the Strapdown INS Accuracy Assessment Criteria upon Flight Test Results.....236

52. Calibration of an Inertial Measurement Unit at Changing Temperature with Simultaneous Estimation of Temperature Variation Coefficients: a Case Study on BINS-RT.....240
   A.V. Kozlov, I.E. Tarygin, A.A. Golovan, I.Kh. Shaymardanov, A.A. Dzuev

53. IMU Calibration Using SINS Navigation Solution: Selection of the Rate Table Motion Scenario.....243
   E.V. Dranitsyna

54. Application of Guaranteed Approach for the Calibration of Accelerometer Unit on High-Precision Motion Simulator.....248
   A.A. Golovan, A.I. Matasov

55. Methods for Testing and Test Results of Inertial Sensors Intended for Operation in Helicopter-Type Aircraft.....251
   R.V. Ermakov, A.N. Popov, E.N. Scripal, D.M. Kalikhman, D.V. Kondratov, A.A. L’vov

56. Self-Calibration of a Digital Odometer Integrated with a Three-Component SINS for a Land Vehicle.....255
   B.V. Klimkovich

57. Progress on Atomic Gyroscope.....259
   Y. Liu, M. Shi, X. Wang

58. Miniature Accelerometer for High-Dynamic, Precision Guided Systems.....266
   J. Beitia, P. Loisel, C. Fell, I.M. Okon

59. Gyroscopic Stabilization System on Micromechanical Sensing Elements.....272
   D.M. Malyutin

60. Hardware and Software Architecture of Multi MEMS Sensor Inertial Module.....276
   A.P. Moschevikin, A. Sikora, P.V. Lunkov, A.A. Fedorov, E.I. Maslennikov

61. MEMS-Based Devices and Systems for Orientation, Stabilization and Navigation.....279
   V.V. Matveev, V.Ya. Raspopov

62. Research on Influence of Pump Laser Frequency Fluctuation on the Bias Drift of Nuclear Magnetic Resonance Gyro.....281
   W.Y. Zhou, X.F. Wang, Y.C. Deng, Y.X. Liu
63. A Micromechanical Gyroscope with Bistable Suspension of Microdrive.....286
   E.N. Pyatyshev, Ya.B. Enns, I.M. Komarevtsev, M. Wurz, A. Glukhovskoy

64. MEMS Gyro Comb-Shaped Drive with Enlarged Capacity Gradient.....289
   E.N. Pyatyshev, Ya.B. Enns, A.N. Kazakin, R.V. Kleimanov, A.V. Korshunov,
   N.Yu. Nikitin

65. Integrated Circuit Layout Design for a Micromechanical Accelerometer.....292
   I.V. Lemko, Ya. V. Belyaev, D. V. Kostygov, N. N. Nevirkovets, Yu.A.
   Andryakov, A.A. Mikhteeva

66. Methods to Increase the Resistance of an Inertial Measurement Unit to External
   Mechanical and Thermal Actions.....295
   A.Yakimova, A. Bocharov, Y. Belyaev, A. Belogurov

67. Measurement Analysis of Multiple MEMS Sensor Array.....298
   M. Schwaab, S.A. Reginya, A. Sikora, E.V. Abramov

68. Solid-State Wave Gyroscope: A New-Generation Inertial Sensor.....302
   S.E. Perelyayev, B.P. Bodunov, S.B. Bodunov

69. Mathematical Model of Motion of a Rotor-type Micromechanical Gyro Sensing
   Element as an Orthotropic Round Plate Clamped at its Center.....305
   M.A. Barulina, V.M. Pankratov, A.V. Krysko

70. Algorithms for Calibration of a MEMS Accelerometer Unit Using an Icosahedron
   Bench Constructed from “MOLI” Meccano.....308
   A.V. Derevyankin

71. A Method Providing Scale Factor Linearity in Compensation Type Angular Rate and
   Linear Acceleration Meters with Digital Feedback and Pulse Width Modulation
   Control of Torque Sensor Electric Current.....312
   L.Ya. Kalikhman, D.M. Kalikhman, V.I. Grebennikov, V.V. Skorobogatov, S.F.
   Nakhov

72. A Method to Measure Linear Output Characteristic of a Compensation Type
   Accelerometer by Means of a “Non-Ideal” Centrifuge.....318
   D.S. Gnusarev, E.A. Deputatova, D.M. Kalikhman, A.S. Chibirev

73. I. Influence of the Upper Limiting Temperature on the Scale Factor of a Compensating
   Pendulum Accelerometer.....321
   Yu. Bykanov, F.R. Fakhretdinov, E.S. Smirnov

74. Design Optimization of a Microgyroscope on Standing Surface Acoustic Waves.....324
   D.P. Lukyanov, A.S. Kukaev, S.Yu. Shevchenko

75. On the Development of the Error Model of Gyroscopes Based on the De Broglie Waves.....327
   N.I. Krobka, N.V. Tribulev, D.A. Turkin
76. Synthesis of Pendulous Accelerometer Feedback Controller Using Linear Matrix Inequalities and Construction of Invariant Ellipsoids.....332
   V.M. Nikiforov, A.A. Gusev, S.S. Zolotukhin, T.A. Zhukova, A.A. Nizhegorodov

77. Identification of Pendulous Accelerometer Mathematical Model Taking into Account Parametric Uncertainty.....335
   V.M. Nikiforov, A.A. Gusev, S.S. Zolotukhin, T.A. Zhukova, A.A. Nizhegorodov

78. Laser Gyros Frequency Biasing and Fiber Optic Gyros Phase Biasing: Similarities and Differences.....339
   N.I. Krobka, D.A. Turkin

79. Mechanical Dither Control Optimization for Laser Gyro with Total Reflection Prisms.....351
   Y. Tao, S. Li, G. Zhou, J. Lin

80. Digital Laser Gyroscope with Lock-in Minimization System.....358
   A.E. Fyodorov, V.A. Zborovskiy, D.A. Rekunov, A.N. Kurylev

81. Multifrequency Laser Gyro and its Operation Regimes.....362

82. Compensation Methods of Ring Resonator Microgyroscope Drift.....365
   A.A. Maslov, D.A. Maslov, I.V. Merkuryev, V.V. Podalkov

83. Simulation of a Slow Beat Frequency Drift in a Large Laser Gyro.....369
   A.S. Bessonov, A.P. Makeev, E.A. Petrukhin

84. A Method of Starting Fiber Optic Gyroscope Outside its Optical Measuring Range.....373
   H. Shi, W. Wang, H. Yu, Z. Zhao

85. The Express Test of Winding Symmetry Quality in FOG Fiber Coils.....377
   M. Li, L. Ma, H. Yu, F. Hui, X.M. Zhang, X.Y. Zhang

86. Investigation on Near Gaussian-Shaped Spectrum Erbium-Doped Fiber Source Which Applied to the Fiber Optic Gyroscope.....381
   F. Hui, M. Li, L. Ma, W. Zuo, S. Zhang, X.M. Zhang

SESSION III – SPACECRAFT CONTROL AND NAVIGATION

87. (Invited)
   Problems and Features of Navigation and Control of Nanosatellites: Experience and Lessons Learned.....385
   I.V. Belokonov, I.A. Timbay, P.N. Nikolaev

88. Algorithm for Reorientation of the CubeSat Nanosatellites.....399
   A.V. Kramlikh, M.E. Melnik
89. Resonant Mechanical Moment During Rotation of a Microsatellite with a Magnet and Flywheels on Board: Features, Time Interval, Measurement Methods.....403
   V.V. Lyubimov

90. Technology for Calibration of Measuring Instruments of SamSat Nanosatellites’ Family.....407
   A.M. Bogatyrev, I.A. Lomaka, P.N. Nikolaev

91. The Algorithm of Relative Orientation for Formation Flight of a Group of Nanosatellites Based on the Radionavigation Ranging Method.....411
   A.M. Bogatyrev, K.E. Shilov

92. Passive Gravitational Aerodynamic Stabilization of Nanosatellite.....415
   I.V. Belokonov, I.A. Timbai, M.S. Kurmanbekov

93. Estimation of the Nanosatellite Attitude and Angular Rate by Analyzing the Navigation Spacecraft Geometrical Visibility Using the Controllable Pattern of Navigation Antenna.....419
   I.V. Belokonov, A.V. Kramlikh, M.E. Melnik

94. Design of Mechatronic Hydrodynamic Damper for Orientation and Stabilization System of Nanosatellite.....423
   D.V. Malygin, Yu.V. Zhigulina

95. Satellite Guidance and Gyromoment Attitude Control at an Area Scanning Land-Survey.....425
   Ye.I. Somov, S.A. Butyrin, S.Ye. Somov

96. Digital Signal Processing in an Astroinertial System for Determining Attitude and Angular Rate of a Maneuvering Land-Survey Satellite.....430
   Ye. I. Somov, S.A. Butyrin

97. Guidance and Digital Attitude Control of a Maneuvering Land-Survey Satellite.....435
   T.Ye. Somova

98. GLONASS Technologies for Controlling the Fields of Short-Range Navigation and Landing Systems.....440
   V.I. Baburov, N.V. Ivantsevich, O.I. Sauta

   O.L. Starinova, R.M. Khabibullin

SESSION IV – METHODS AND MEANS OF GRAVITY FIELD MEASUREMENT

100. (Invited)
    Satellite Methods of Gravity Field Study. Status and Development Prospects.....448
    V.E. Kosenko, V.D. Zvonar, S.G. Revnivykh
101. High-Accuracy Determination of the Earth's Gravitational Field Parameters Using Automated Zenith Telescope.....462
   S.V. Gayvoronsky, N.V. Kuzmina, V.V. Tsodokova

102. Autonomous Underwater Robot as an Ideal Platform for Marine Gravity Surveys.....466
   L.V. Kiselev, A.V. Medvedev, V.B. Kostousov, A.E. Tarkhanov

103. Direct Compensation and Kalman Filter Compensation of Gravity Vertical Deviation Based on Grid Database.....469
   X. Mu, T.Y. Shao, Q.W. Fu, S.H. Li, F.E. Zhang

   Yu.V. Bolotin, V.S. Vyaz'min